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# TL-5200 Motion Control User Manual

Laser Motion Control



2018.11

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# Introduction

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## User Manual

By reading this instruction, the users will know the basic composition, installation and how to use TL-5200.

## **For Who**

This manual is applicable to engineers who have a certain understanding of laser mechanical automation and electrical circuits.

## **Main Content**

The composition, installation and use of TL-5200 are introduced in detail

## **Relevant Document**

《LaserCAD User Manual》

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# 1. Product Introduction

## 1.1 System Introduction

TL-5200 is a universal motion controller for laser cutting, laser engraving and other fields developed by Shenzhen Trocen Automation Tech co., LTD. This controller supports auto-distribute double-head cutting and used for Advertising, clothing, leather, auto decoration, fabric, embroidery and acrylic cutting fields. This system is used by LaserCAD software and motion controller, which greatly improves the production efficiency and reduces the production cost.

### Features of LaserCAD

- User-friendly and versatile.
- Support CorelDraw, Auto CAD and other professional drawing software.
- Support the file format: AI, PLT, DXF, SVG, PDF, NC, DST, DSB, UD5, BMP, GIF, JPG, JPEG, PNG.
- Simple graphics drawing function.
- Support Z AutoFocus function.

### Features of Wiring Board

- High DSP, quick calculating and optimal algorithm.
- 4.3'' color TFT LCD display with concise operation interface.
- Optical coupler, anti-electromagnetic interface and system stability.

- Faster reading files under USB, U Disk and network.
- Support auto-distribute double-head cutting

## 1.2 Terms and Explanation


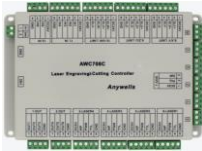





Table1-2-1 Terms and Explanation

Term	Explanation
LaserCAD Software	LaserCAD is a complementary software with auto typesetting for laser motion control.
TFT LCD Panel LCD Panel Control Panel Panel (Mainboard)	4.3" color TFT LCD control panel. The panel is used for specific display and control operations and it is an important part of the system.
Wiring board (Baseboard)	The baseboard is the control board of the integrated signal (input and output) control and the motor drive connection.
Hardware	Includes: mainboard, wiring board, wire and so on.

## 1.3 Unpack

After receiving the product, please confirm whether the product and accessories are complete. If there is a lack of accessories, please contact the after-sales service of Trocen company.

**Table1-3-1 Wire Introduction**

Name	Appearance	Introduction
Panel and mainboard		The panel (mainboard) of TL-5200.
Wiring Board		The wiring board of TL-5200.
USB Cable (3m)		Connect computer and panel by USB.
Network Cable (5m)		Connect computer and panel by network.
CN1 (1.6m)		Connect the CN1 port of main board and panel.
CN2 (1.6m)		Connect the CN2 port of main board and panel.
8 PIN (1m)		Patch cord with USB and network port.

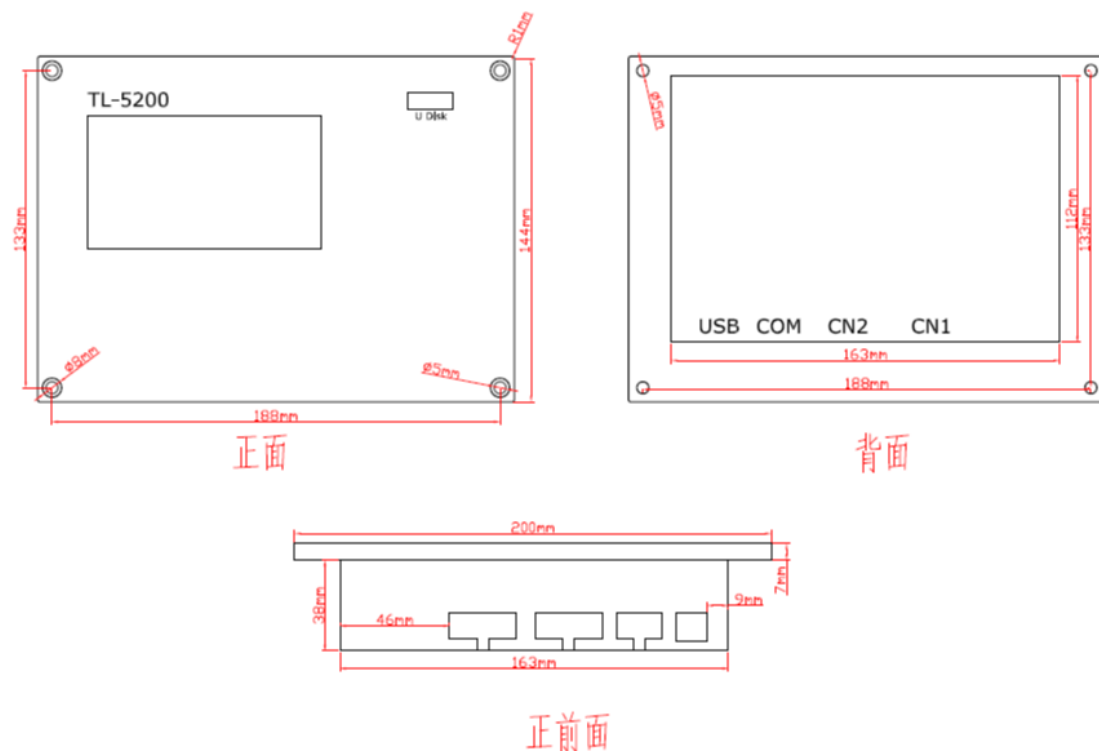
## 1.4 Panel Preview

There are LCD display, soft keys and U disk slot on panel.

Figure1-4-1 Panel Preview



**Figure1-4-2 Size of Main Board**



## 1.5 Buttons




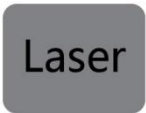




According to the different use of keys, all keys are roughly divided into three categories: function keys, number keys and direction keys.



### 1.5.1 Function Keys

Function key is designed to directly realize a specific operation function.

**Table1-5-1 Function Keys Instruction**

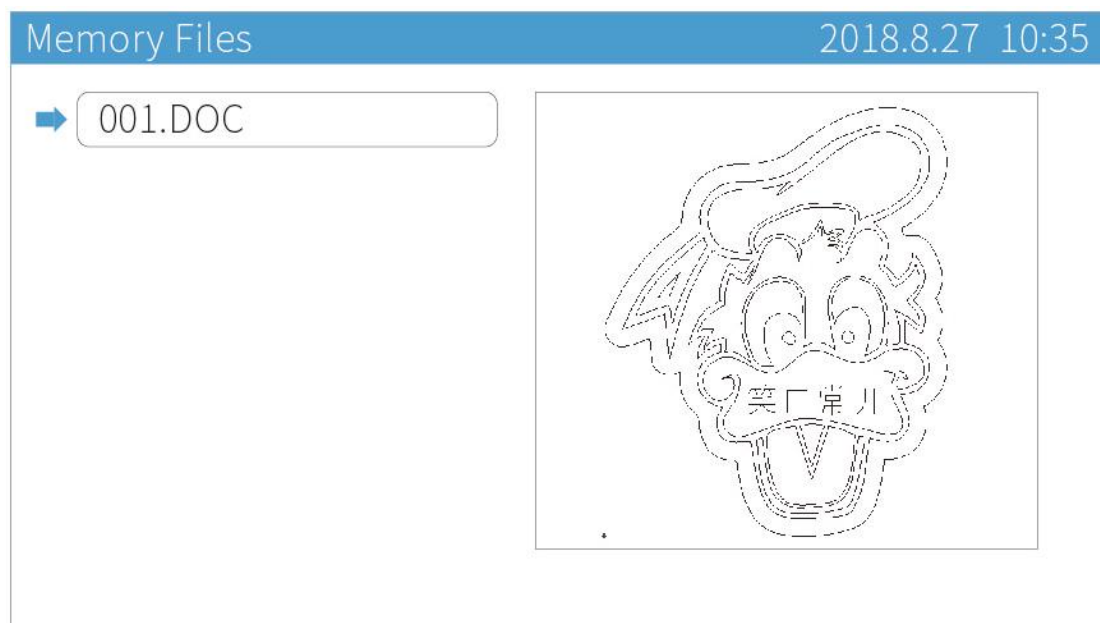
Name	Icon	Instruction
Reset		No matter what the state of the machine is in, pressing this button will make it enter the

		resetting state.
Menu		Show the main menu.
File		Browse the files stored in the control board.
Origin		Setting machine's starting point of the current file.
Laser		Test usage. Press the key, the laser tube will give out light. It's used to adjust optical path.
Box		Frames the working area from the origin point of the current file.
Stop		Once pressed, the machine will stop its current function and move back to its origin. Press <b>【Stop】</b> + direction keys to switch the speed of axis movement, quick to slow or slow to quick.
Start/Pause		Pause the machine and keep it stay at location. Press again to resume.
Shift		Combine function key.

Esc		Exit edit mode (Exit cursor). Return to previous menu.
Enter		Enter edit mode (Start cursor). Confirm the current operation.

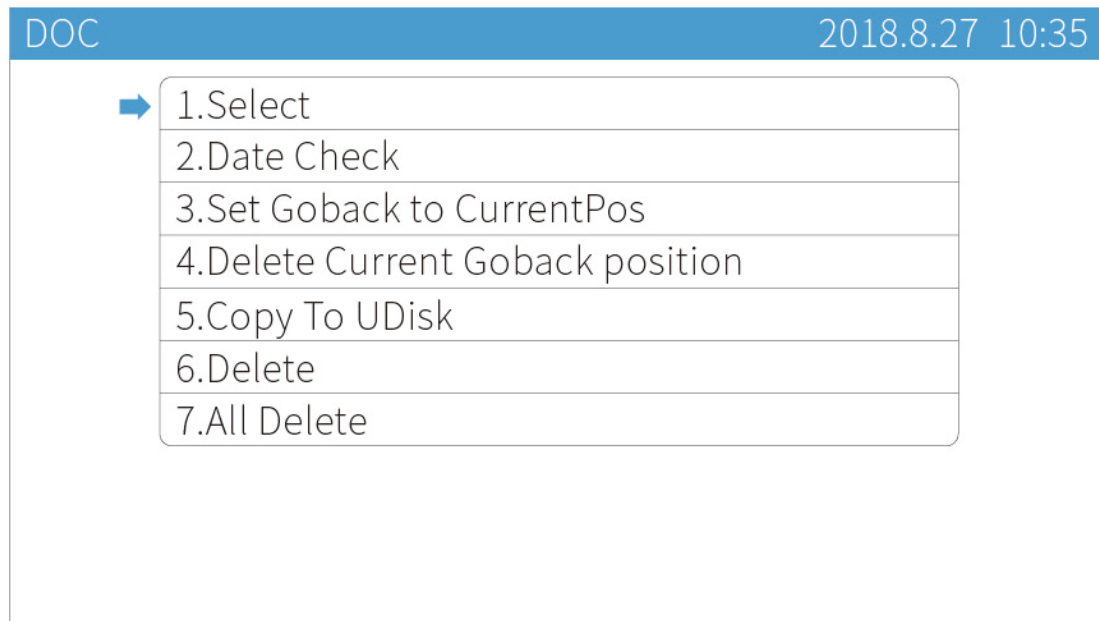
On the main page, press **【File】** and you could see the memory files stored in the mainboard.

**Figure1-5-1 File Interface**



Move cursor to the file you need, press **【Enter】** , you could set the file parameters.

**Figure1-5-2 File Parameters Setting Page**



- Move cursor to **【Select】** , press **【Enter】** and set current file as work file.
- Move cursor to **【Data Check】** , press **【Enter】** . If the graphics is the same as that in PC, the system will prompt “File Data OK!”, then the graphics will be allowed to process. If not, the machine won’t process this graphics.

Figure 1-5-3 File Format Test



Users can set other parameters as need.

### 1.5.2 Direction Keys

- **【↑】【↓】【←】【→】**

They are used to move the motion axis and cursor, also used to modify options in the current view.

- **【Z↑】【Z↓】**

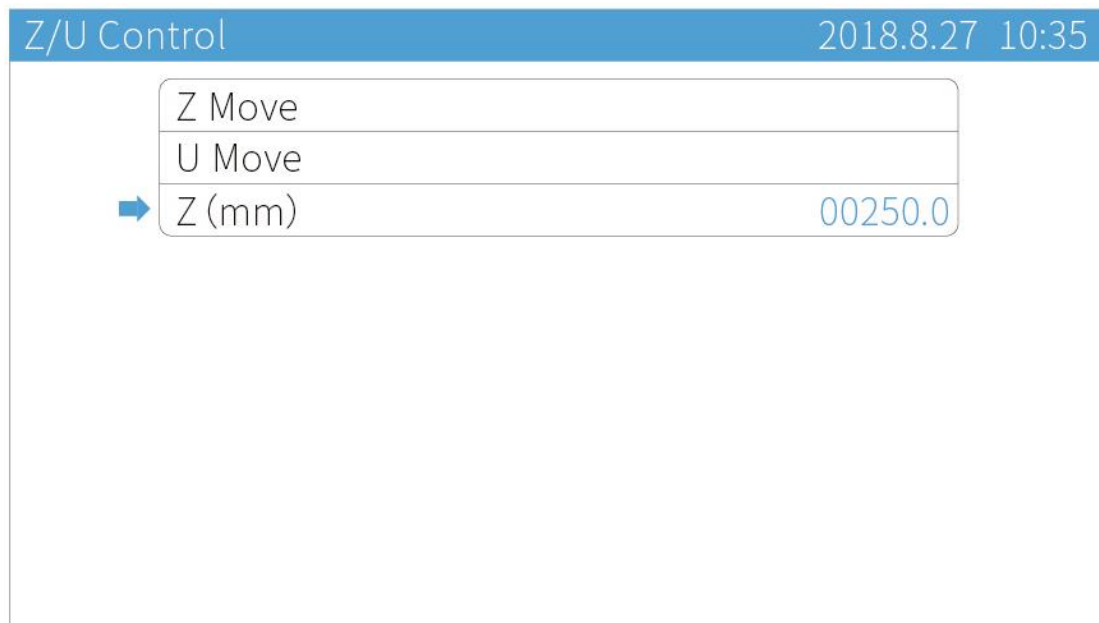
Move cursor when the direction keys **【↑】【↓】【←】【→】** are occupied, and these two keys are used to move Z axis directly.

- **【Z/U】**

Enter the **Z/U Control** page, press **【Z↑】【Z↓】** to move cursor and press **【↑】【↓】【←】【→】** to move Z/U axis. **【Z(mm)】** shows the

current coordinate value. Users can move U axis, but the coordinate of U axis will not change and it is “0” forever.

**Figure 1-5-4 Z/U Control Interface**



### 1.5.3 Number Keys

Used to modify parameter values. 【0】 and 【C】 keys also can be used to move feeding axis (U axis).

## 1.6 Wiring Board

The panel and other parts of machine are connected by wiring board. The components as below:

- Connect motor driver
- Detection of motion axis limit signal
- Input signal detection
- Output IO control signal and corresponding power supply

### 1.6.1 Wiring Board Appearance

### Figure1-6-1 Wiring Board Appearance

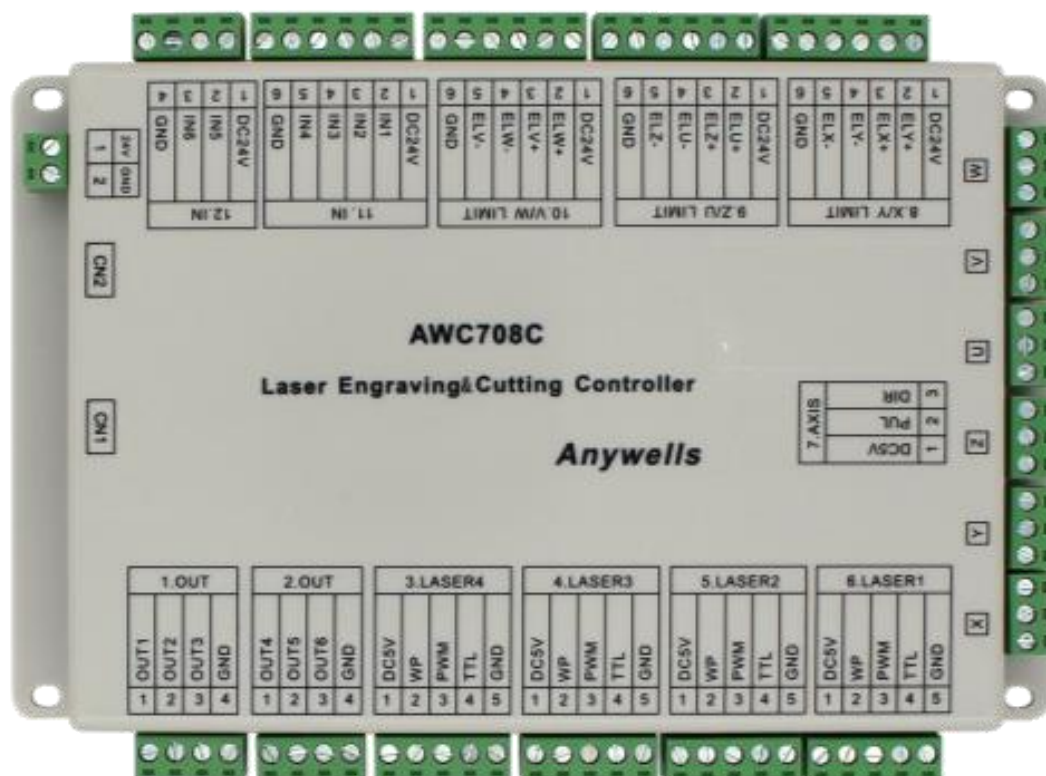
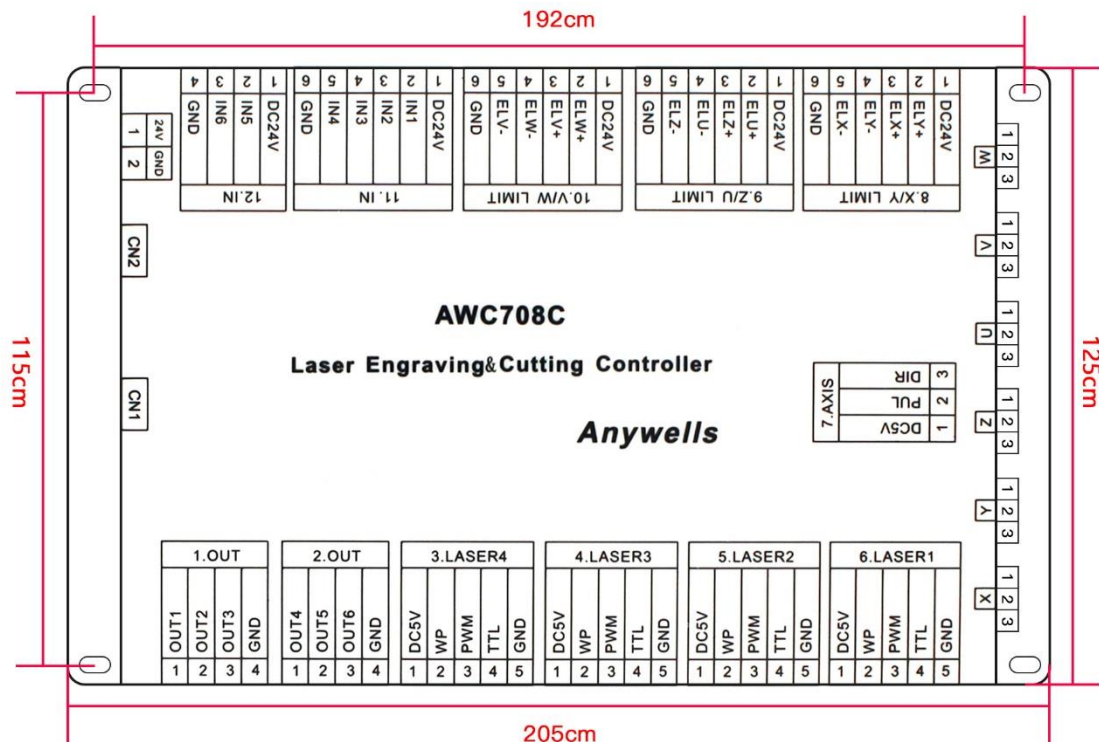


Figure1-6-2 Wiring Board Ports Introduce



## 1.6.2 Port Instruction

### 1.6.2.1 Power Supply Port

The power supply ports provide power to wiring board and panel. Please pay more attention to polarity when connect them. Don't make the polarity reverse.

Table1-6-1 Instruction of Wiring Board Power Supply Port

Pin	Name	Introduction
1	+24V	24V positive polarity.
2	GND	Negative pole.

### 1.6.2.2 Port of Panel and Wiring Board

Connect panel and wiring board with CN1 and CN2 cables.

**Table1-6-2 Port of Panel and Wiring Board**

Name	Introduction
CN1	Connect CN1 port of panel and wiring board with CN1 cable.
CN2	Connect CN2 port of panel and wiring board with CN2 cable.

### 1.6.2.3 Signal Input

There are two groups of signal input ports.

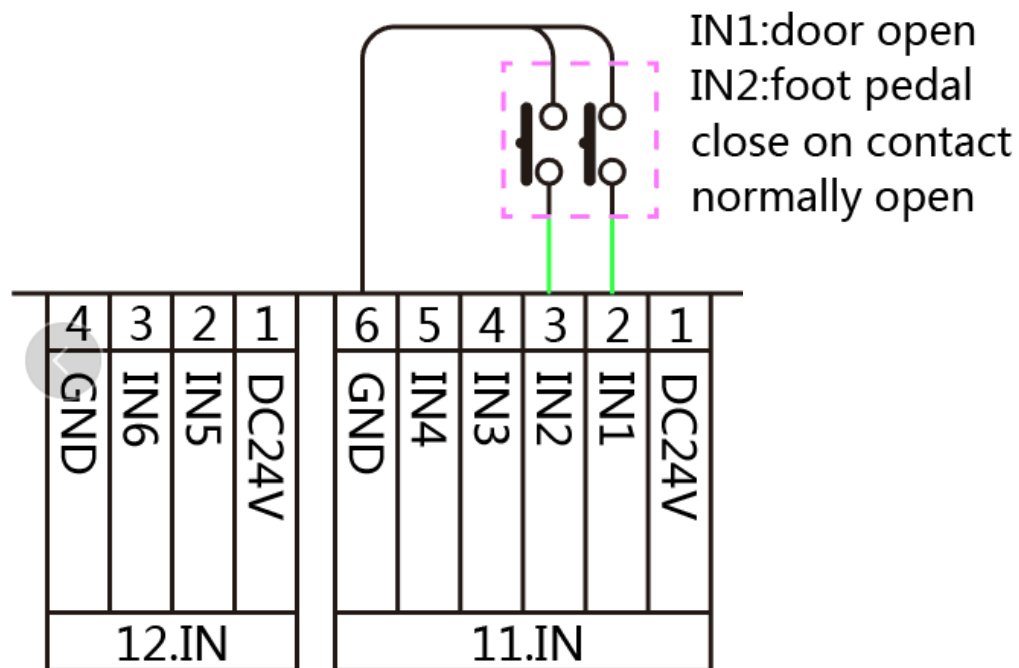
**Table1-6-3 Wiring Board Signal Input Port Instruction**

	PIN	Name	Instruction
11.IN	1	DC24V	Output DC voltage (24V)
	2	IN1	Door open protection signal (This function needs to be turned on in the panel to be effective).
	3	IN2	Foot switch (This function needs to be turned on in the panel to be effective).
	4	IN3	Reserved
	5	IN4	Reserved
	6	GND	Power ground

12.IN	1	DC24V	Output DC voltage (24V)
	2	IN5	Reserved
	3	IN6	Reserved
	4	GND	Power ground

Wiring diagram of signal input:

Figure1-6-3 Wiring Diagram for Signal Input



#### 1.6.2.4 Signal Output

There are two groups of output ports to supply power and control signals. If you choose OUT2 (Blow when laser is power on), you must set the parameters of **【Blow Open Delay】** or **【Blow Close Delay】** on the **Common**

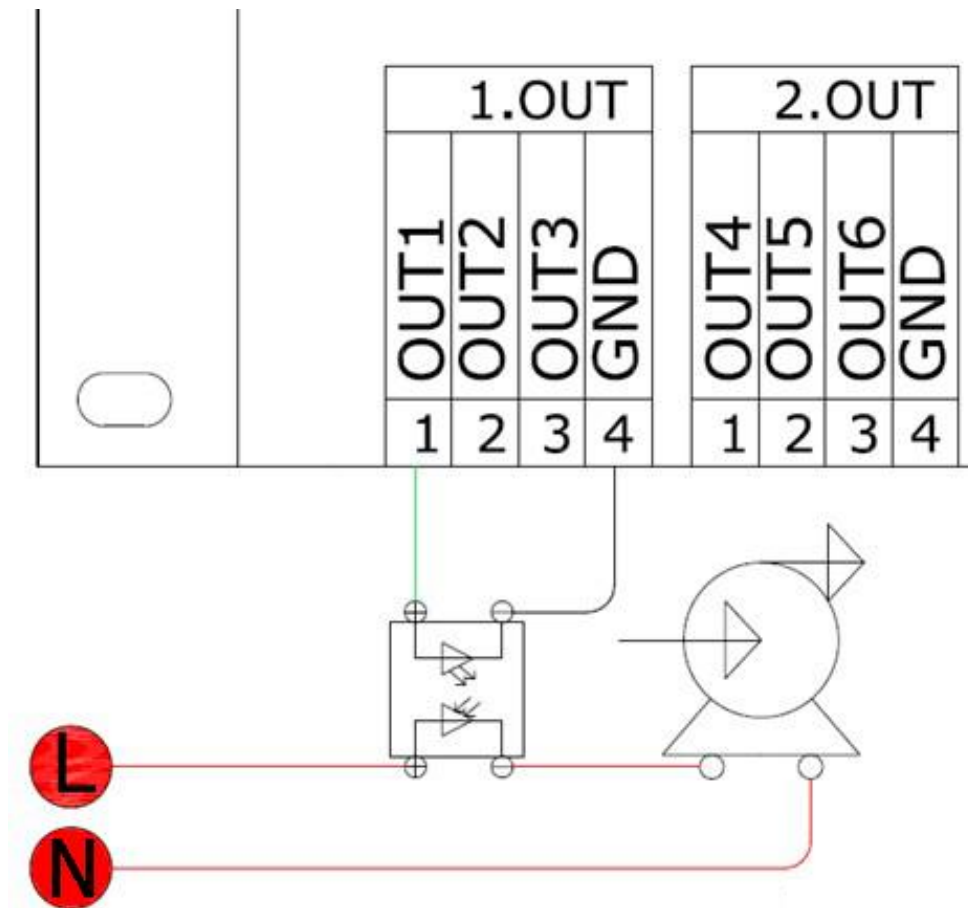
**Parameter** interface, with the minimum value of 0.01.

**Table1-6-4 Output Port Instruction**

	PIN	Name	Instruction
1.OUT	1	OUT1	Blowing signal (blow all the working time):  OUT1 Blowing when output is high logic level.  OUT1 Do not blow when output is low logic level.
	2	OUT2	Blowing signal (blow when laser is powering on):  OUT2 Blowing when output is high logic level.  OUT2 Do not blow when output is low logic level.
	3	OUT3	Reserved
	4	GND	Power ground (OUT).
2.OUT	1	OUT4	Reserved
	2	OUT5	Reserved
	3	OUT6	Reserved
	4	GND	Power ground (OUT).

Output signals control laser blowing generally. The wiring diagram is shown below (blow all the working time).

**Figure1-6-4 Blowing Control Diagram**



#### 1.6.2.5 Laser Power Supply Port

The wiring board provides 4 groups of laser output control ports.

**Table1-6-5 Laser Controller Output Instruction**

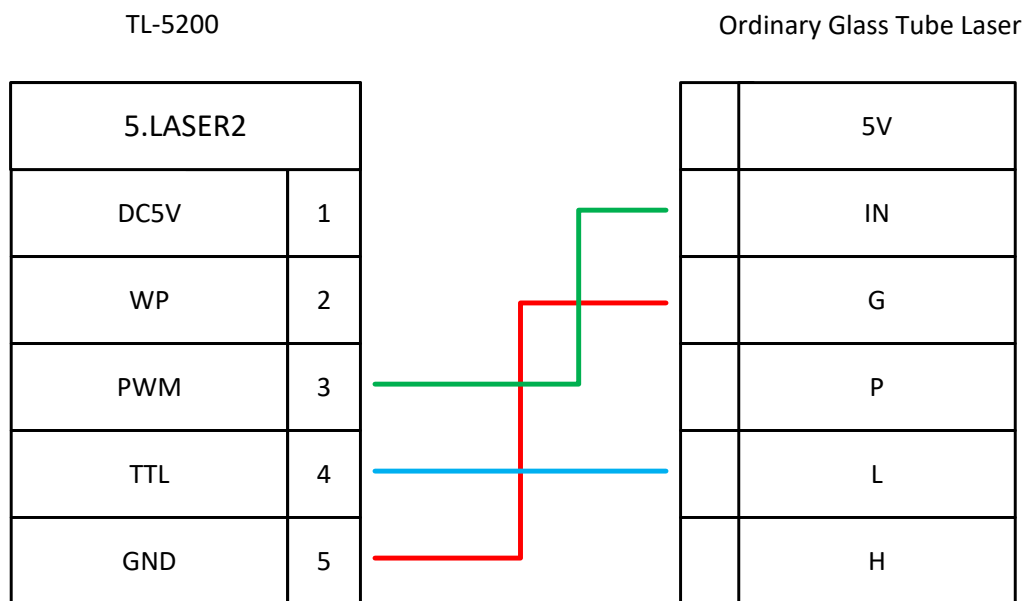
	PIN	Name	Instruction
3.Laser4	1	DC5V	Output DC voltage (5V).
	2	WP	Water Protection.

	3	PWM	Digital signal. The output voltage is 0~5V, and it will change according to the power.
	4	TTL	Laser switch signal.
	5	GND	Power ground.
4.Laser3	1	DC5V	Output DC voltage (5V).
	2	WP	Water Protection.
	3	PWM	Digital signal. The output voltage is 0~5V, and it will change according to the power.
	4	TTL	Laser switch signal.
	5	GND	Power ground.
5.Laser4	1	DC5V	Output DC voltage (5V).
	2	WP	Water Protection.
	3	PWM	Digital signal. The output voltage is 0~5V, and it will change according to the power.
	4	TTL	Laser switch signal.
	5	GND	Power ground.
6.Laser1	1	DC5V	Output DC voltage (5V).
	2	WP	Water Protection.
	3	PWM	Digital signal. The output voltage is 0~5V, and it

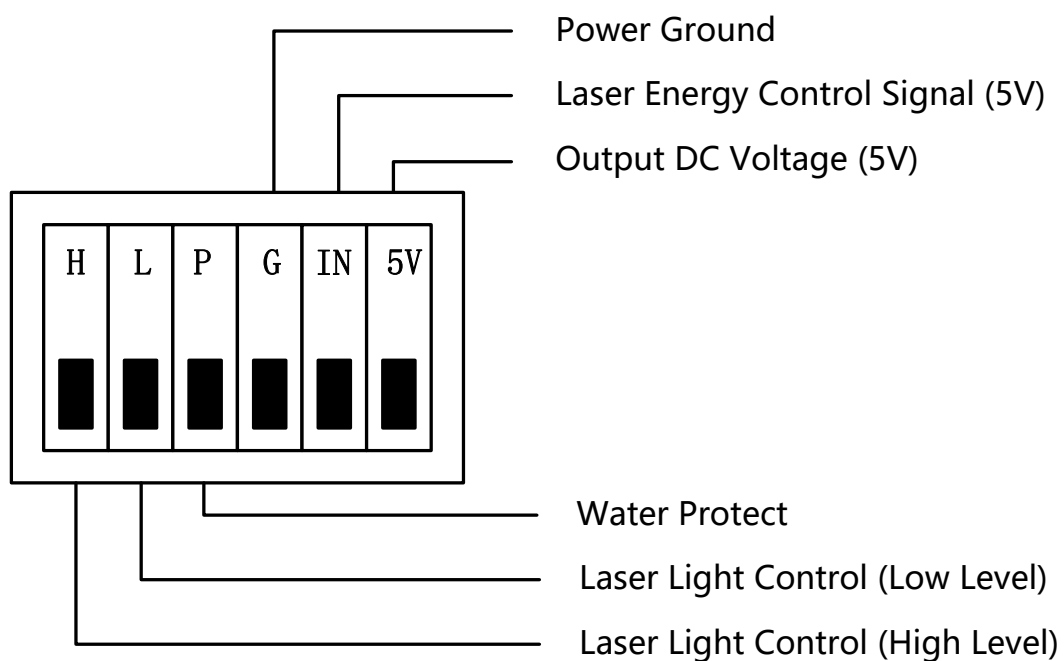
			will change according to the power.
	4	TTL	Laser switch signal.
	5	GND	Power ground.

Different lasers have different connection modes. Take ordinary glass tube laser as example. The optical signal of ordinary glass tube laser is 5V, and set low level for light emitting. The power signal PWM of main board is connected to the IN pin of laser power source and TTL to the L pin of laser power source. All signals have uniqueness, which is connected to this group of signals, other pins do not need to be connected. You could connect the water tank by the WP pin (water protection) of the main board or the P pin (water protection) of laser power supply, and please pay attention that you could only choose one of them. For the RF tube laser power supply, only connect the PWM of the main board to the IN pin, GND to G pin, and no need to connect TTL pin.

**Figure1-6-5 Ordinary Glass Tube Laser Diagram**



**Figure1-6-6 Pins of Laser Power Source**



If the laser light control signal is low level, connect the L pin of laser power,

and if the laser light control signal is high level, connect the H pin of laser power.

#### 1.6.2.6 Motor Drive Control Port

The wiring board can provide up to 6 motor driver connections, and users can choose step driver or servo driver according to the need. The servo driver has higher control accuracy than step driver. Users can choose the appropriate driving mode according to the usage scenario, cutting precision requirements and cost factors. We take the step driver as an example. [Various types of servo driver wiring diagram, please refer to Appendix 1 of this article.](#)

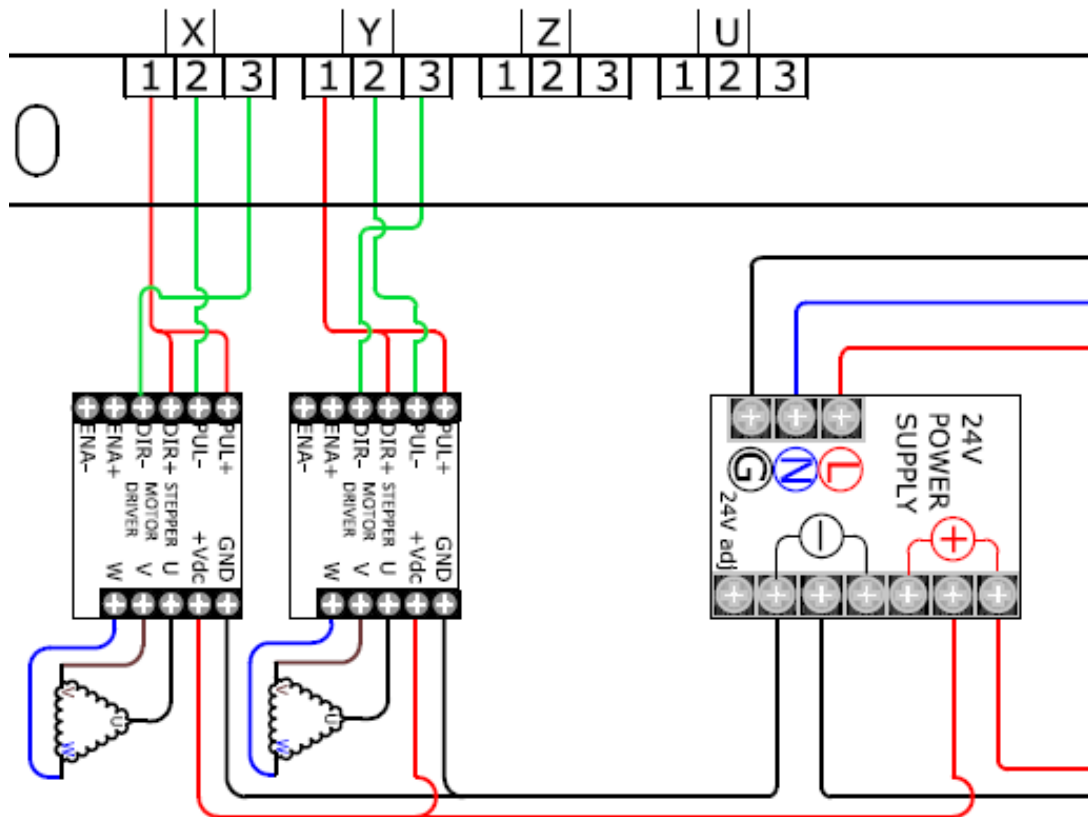
Table1-6-6 Motor Driver Connection Instruction

	PIN	Name	Instruction
X	1	DC5V	Output DC voltage (5V)
	2	PUL	Pulse signal
	3	DIR	Direction signal
Y	1	DC5V	Output DC voltage (5V)
	2	PUL	Pulse signal
	3	DIR	Direction signal
Z	1	DC5V	Output DC voltage (5V)
	2	PUL	Pulse signal

	3	DIR	Direction signal
U	1	DC5V	Output DC voltage (5V)
	2	PUL	Pulse signal
	3	DIR	Direction signal
V	1	DC5V	Output DC voltage (5V)
	2	PUL	Pulse signal
	3	DIR	Direction signal
W	1	DC5V	Output DC voltage (5V)
	2	PUL	Pulse signal
	3	DIR	Direction signal

The diagram below shows the connection of step driver.

Figure1-6-7 Diagram of Driver Connection



### 1.6.2.7 Limit Signal

The wiring board provides 6-way sensor limit signal access. Each axis supports maximum and minimum coordinate limit signal input. This system supports working range limitation, so users do not need to install hard limit sensor, just set the **【Range】** parameter on the **Axis Parameters** page. [More details about \*\*【Range】\*\* , please refer to the Chapter 3.6 of this article.](#)

**Table1-6-7 X/Y Limit Signal Input**

	<b>PIN</b>	<b>Name</b>	<b>Instruction</b>
8.X/Y Limit	1	DC24V	Output DC voltage (24V).
	2	ELY+	The hard limit of Y axis. The input signal of hard limit sensor, when Y axis moves to the maximum coordinate position.
	3	ELX+	The hard limit of X axis. The input signal of hard limit sensor, when X axis moves to the maximum coordinate position.
	4	ELY-	The origin limit of the Y axis. The input signal of origin limit sensor, when the Y axis moves to the minimum coordinate position (zero position).
	5	ELX-	The origin limit of the X axis. The input signal of origin limit sensor, when the X axis moves to the minimum coordinate position (zero position).
	6	GND	Power ground.

**Table1-6-8 Z/U Limit Signal Input**

	<b>PIN</b>	<b>Name</b>	<b>Instruction</b>
9.Z/U Limit	1	DC24V	Output DC voltage (24V).

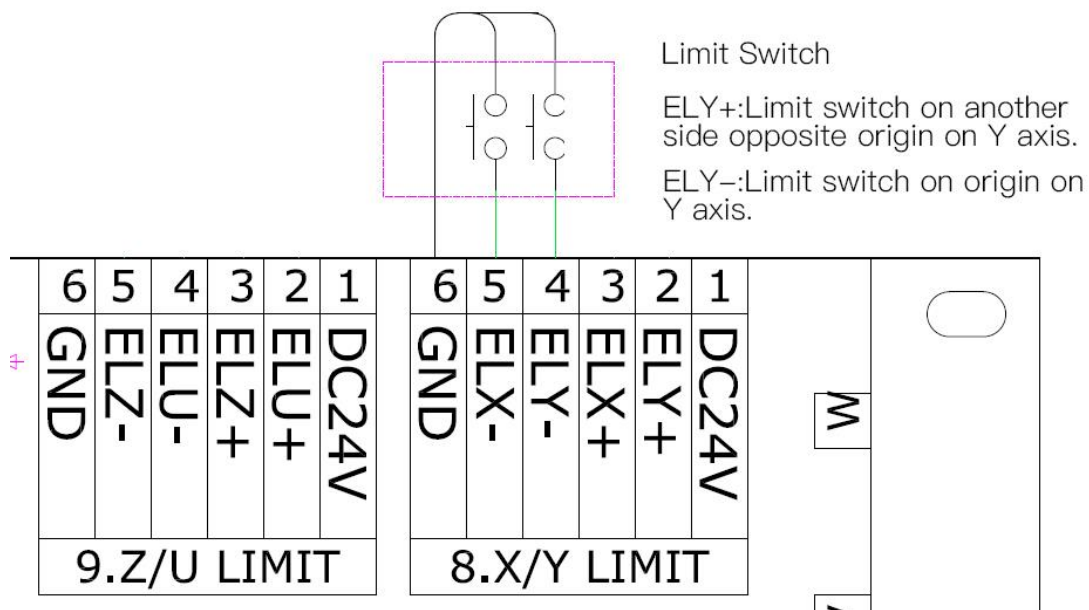
	2	ELU+	The hard limit of U axis. The input signal of hard limit sensor, when U axis moves to the maximum coordinate position.
	3	ELZ+	The hard limit of Z axis. The input signal of hard limit sensor, when Z axis moves to the maximum coordinate position.
	4	ELU-	The origin limit of the U axis. The input signal of origin limit sensor, when the U axis moves to the minimum coordinate position (zero position).
	5	ELZ-	The origin limit of the Z axis. The input signal of origin limit sensor, when the Z axis moves to the minimum coordinate position (zero position).
	6	GND	Power ground.

**Table1-6-9 V/W Limit Signal Input**

	PIN	Name	Instruction
10.V/W Limit	1	DC24V	Output DC voltage (24V).
	2	ELW+	The hard limit of W axis. The input signal of hard limit sensor, when W axis moves to the maximum coordinate position.
	3	ELV+	The hard limit of V axis. The input signal of hard

			limit sensor, when V axis moves to the maximum coordinate position.
	4	ELW-	The origin limit of the W axis. The input signal of origin limit sensor, when the W axis moves to the minimum coordinate position (zero position).
	5	ELV-	The origin limit of the V axis. The input signal of origin limit sensor, when the V axis moves to the minimum coordinate position (zero position).
	6	GND	Power ground.

Figure1-6-8 Diagram of Limit Signal



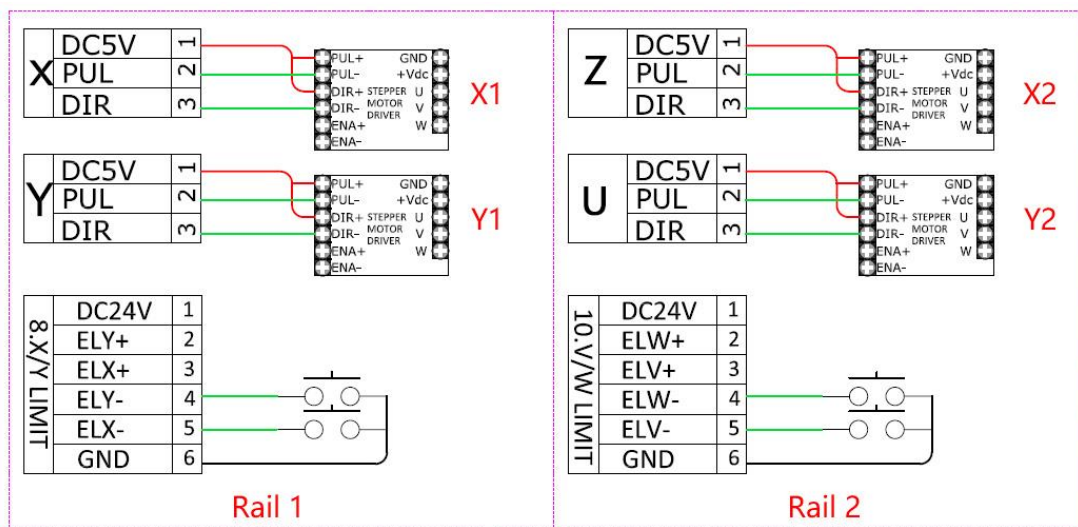
## 1.7 Basic Wiring

TL-5200 series is able to work with the structure of basic double rails and double rails moving separately. The wiring connection of driver and laser varies a little by mechanical structure, but it is the same connecting with limit signal wiring except detecting port is different.

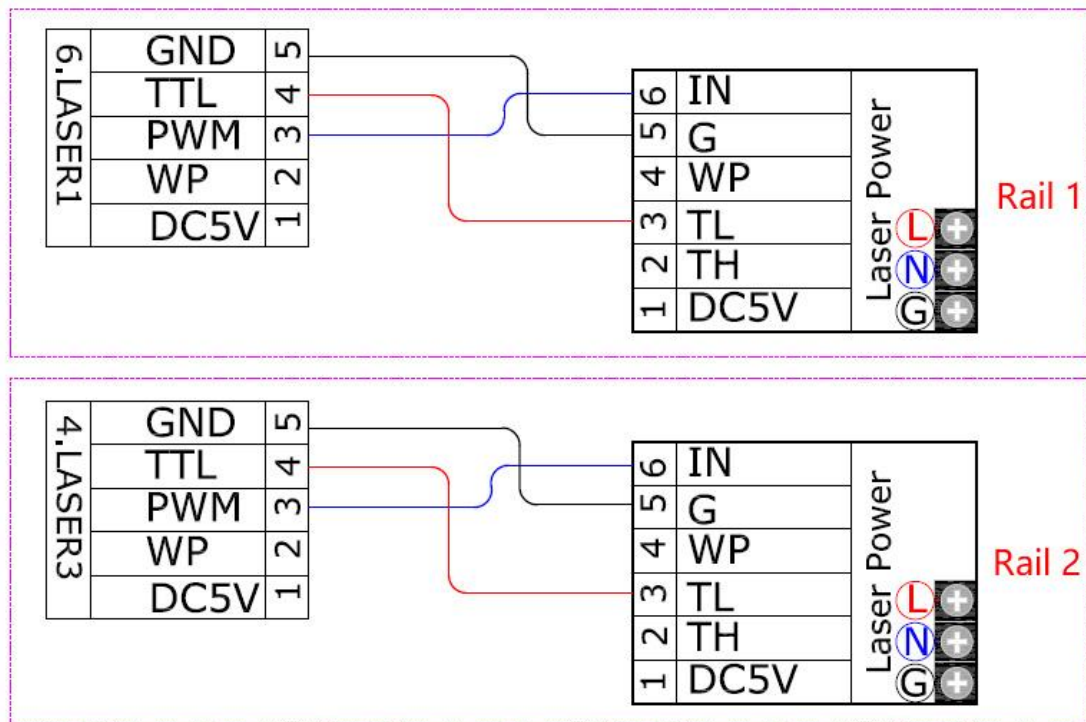
### 1.7.1 Basic Double Rails

There are two rails while single rail with only one laser head, which means only 4 drivers are needed. 4 ports of limit signal controls 2 laser heads.

Figure1-7-1 Motor & Limit Switch Wiring



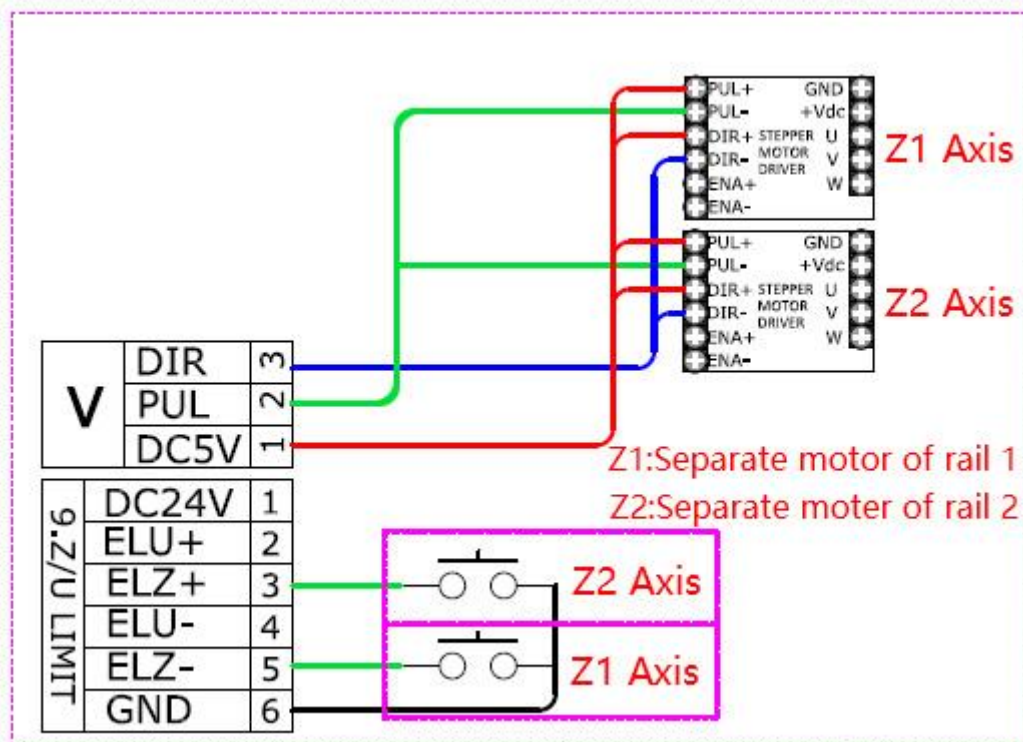
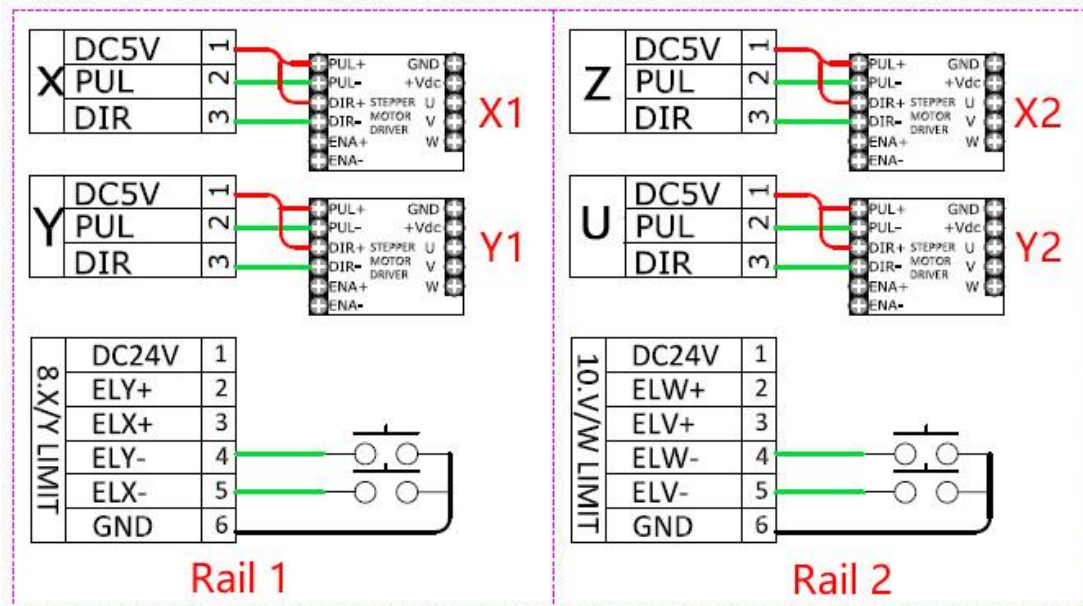
**Figure1-7-2 Laser Power Supply Wiring**



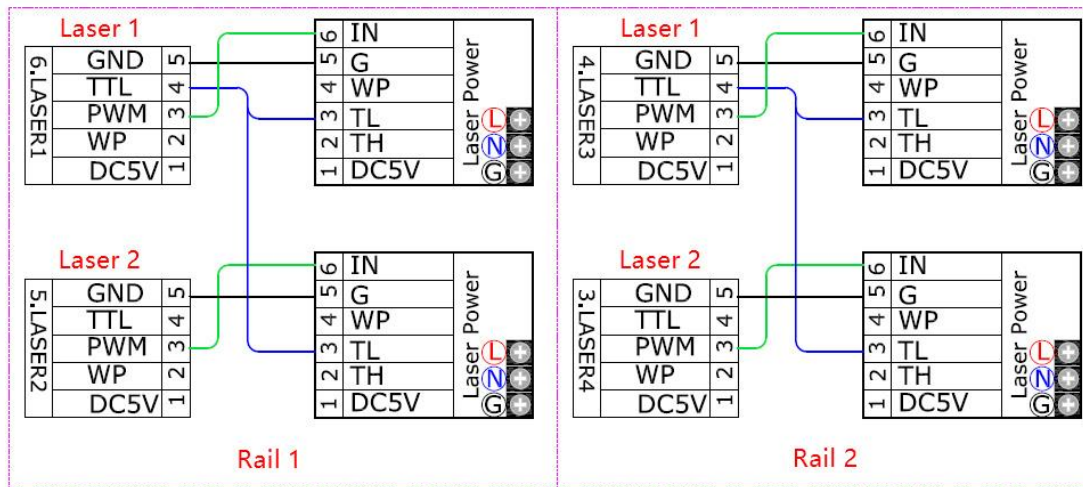
### 1.7.2 Double Rails Moving Separately

Double rails with two laser heads which are available to move freely on each rail. 6 motors, 6 limit signal ports and 4 laser heads are required for this kind of structure, however, 5 motors in total can also meet the needs if we combine two motors controlling two rails into one.

Figure1-7-3 Motor & Limit Switch Wiring



**Figure1-7-4 Laser Power Supply Wiring**



## 2. LaserCAD Installation

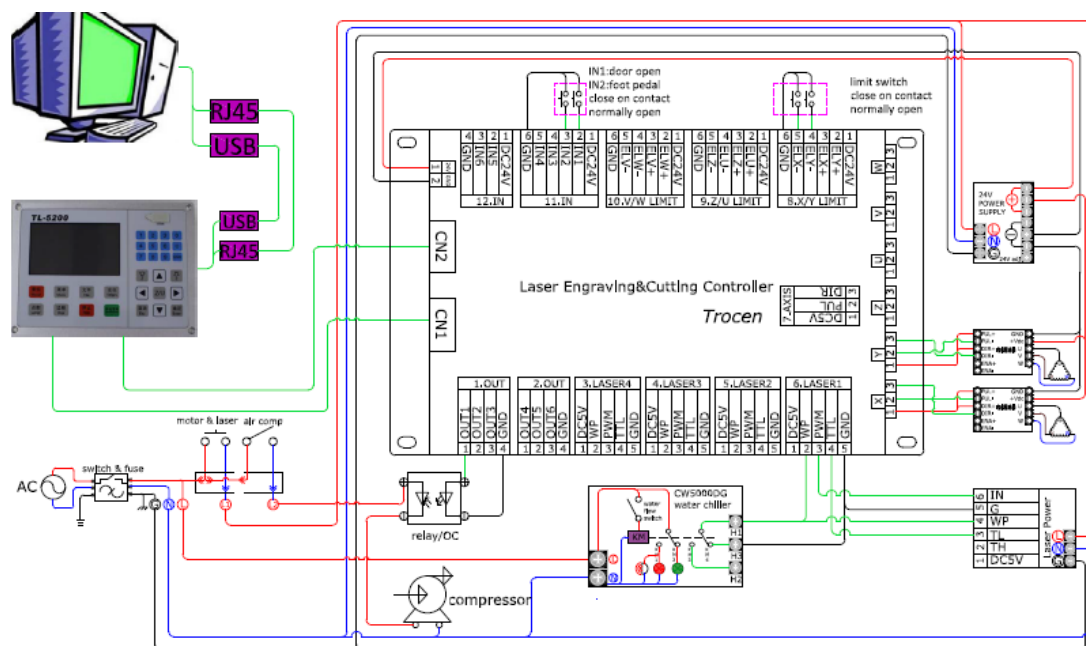
You can go through 《LaserCAD User Manual》 for more details about installation and how to use LaserCAD.

## 3. Simplified Installation

The content of this chapter is mainly about the hardware initial installation of the product and the setting of basic software parameters. Please refer to the following chapters for the detail settings and descriptions of other parameters.

### 3.1 Hardware Connection

Figure3-1-1 Integral Wiring Diagram



- Figure 3-1-1 shows the diagram of ordinary glass tube laser.
- Connect the blow control ports to corresponding electromagnetic valves to control blow.
- Connect the axis limit ports to corresponding axis limiters.

- Please [refer to the Chapter 1.6.2.6](#) to know more detail about X/Y/Z/U/V/W motor driver connection.

## 3.2 Input Test

On the main page, press **【Stop】** and press **【Menu】** two times at the same time, you will see the **Input Test** interface.

Figure3-2-1 Input Test Interface

Input		2018.8.27 10:35	
X-Limit	1	W+Limit	0
X+Limit	1	IN1	1
Y-Limit	1	IN2	1
Y+Limit	1	IN3	1
Z-Limit	1	IN4	1
Z+Limit	1	WP 1	1
V-Limit	1	WP 2	1
V+Limit	0	WP 3	1
W-Limit	1	WP 4	1

According to different types of sensors, you could choose metal products or other shielding objects to close to the sensors in order to detect whether the signals changes, so as to confirm whether the wiring is accurate and effective.

## 3.3 Set the Origin Point of Machine

Connect machine and wiring board as Figure3-1-1. Power on and observe

the motion of axis. If the axis moves random, please press **【Stop】** at once. Check your installation and wiring of limiters, if no mistake, then modify the direction of origin point and reset machine.

On the main page, press **【Stop】** and **【Shift】** at the same time to enter the **Manufacture Parameters Settings** page. Users could set axis parameters (Datum direction/Key direction/Limit Polarity and so on) on the **Axis Parameters** page.

Figure3-3-1 Axis Parameters Interface

X Axis Parameters		2018.8.27 10:35
➡	Distance Per Pulse (um) ...	06.500000
	Valid Pulse Edge	Failling Edge
	Datum Direction	Negative
	Key Direction	Negative
	Limit Polarity	Negative
	Range (mm)	00500
	Start Speed (mm/s)	15.0
	Max Acc (mm/s <sup>2</sup> )	10000
	Max Speed (mm/s)	0500.0
	X2 Distance Per Pulse(um)...	06.500000

Reset the machine, and observe the motion direction of axis again. Before start, please make sure to enable the axis auto reset function. [Detail settings refer to Chapter 7.4.](#)

### 3.4 Key Direction

On the main page, press **【↑】【↓】【←】【→】** to move motion axis, and

check whether the motion direction is the same as key direction. If not, please modify the **【Key Direction】** on the axis parameters page.

### 3.5 Distance Per Pulse

Distance per pulse refers to the actual distance of motion axis for each pulse instruction sent by the controller.

#### 1. The calculation of distance per pulse (Basic double rails)

- 1) Open the **【XY AutoReset】** function, and reset machine, then mark the current position of laser head with A.
- 2) On the main page, press **【Menu】** and enter the ***Jog Control*** page. Set the **【Jog Distance】** to 200mm as example. Then press **【Enter】** to save your modification. If you did not set the **【Range】** on ***Axis Parameters*** page, please do not set the **【Jog Distance】** value too large.
- 3) On the ***Jog Control*** page, move cursor to **【X/Y Jog】**, then press direction key (**【←】/【→】**) one time to make the laser head move a jog distance on the X direction. Mark the current position of laser head with B.
- 4) Measure the distance between A and B, then input the value into **【Actual Length】**.
- 5) On the main page, press **【Stop】+【Shift】** at the same time to open the ***Manufacture Params Settings*** page. Then move cursor to **【Axis Parameters】** option and press **【Enter】**. Then open the ***X Axis***

**Parameters** page and move cursor to **【Distance Per Pulse】** , press **【Enter】** . Input 200mm into **【Expected Length】** and input the distance between A and B into **【Actual Length】**. Then press **【Enter】**, the distance per pulse of X axis will be calculated.

- 6) The calculation methods of distance per pulses of Y/Z/U/W axis is the same as X axis.

## 2. Distance per pulse of V axis (Double rails moving separately)

- 1) Open the **【Z AutoReset】** function, and reset machine. Press **【Laser】** , then mark the position of laser head2 with A.
- 2) On the main page, press **【Menu】** and enter the **Jog Control** page. Set the **【Jog Distance】** to 200mm as example. Then press **【Enter】** to save your modification. If you did not set the **【Range】** on **Axis Parameters** page, please do not set the **【Jog Distance】** value too large.
- 3) On the **Jog Control** page, move cursor to **【Z Jog】** , then press direction key ( **【←】** / **【→】** ) one time to make the laser heads move a jog distance on the X direction. Then press **【Laser】** and mark the position of laser head2 with B.
- 4) Measure the distance between A and B, then input the value into **【Actual Length】** .
- 5) On the main page, press **【Stop】** + **【Shift】** at the same time to open the **Manufacture Params Settings** page. Then move cursor to **【Axis Parameters】** option and press **【Enter】** . Then open the **Z Axis**

**Parameters** page and move cursor to **【Distance Per Pulse】** , press **【Enter】** . Input 200mm into **【Expected Length】** and input the distance between A and B into **【Actual Length】**. Then press **【Enter】**, the distance per pulse of Z axis will be calculated.



When the pulse distance value of any axis is close to or less than 1, the pulse distance can't be adjusted and is always 1. Users need to adjust pulse of motor driver first, then measure the distance per pulse again. The recommended pulse distance value is 5 or more.

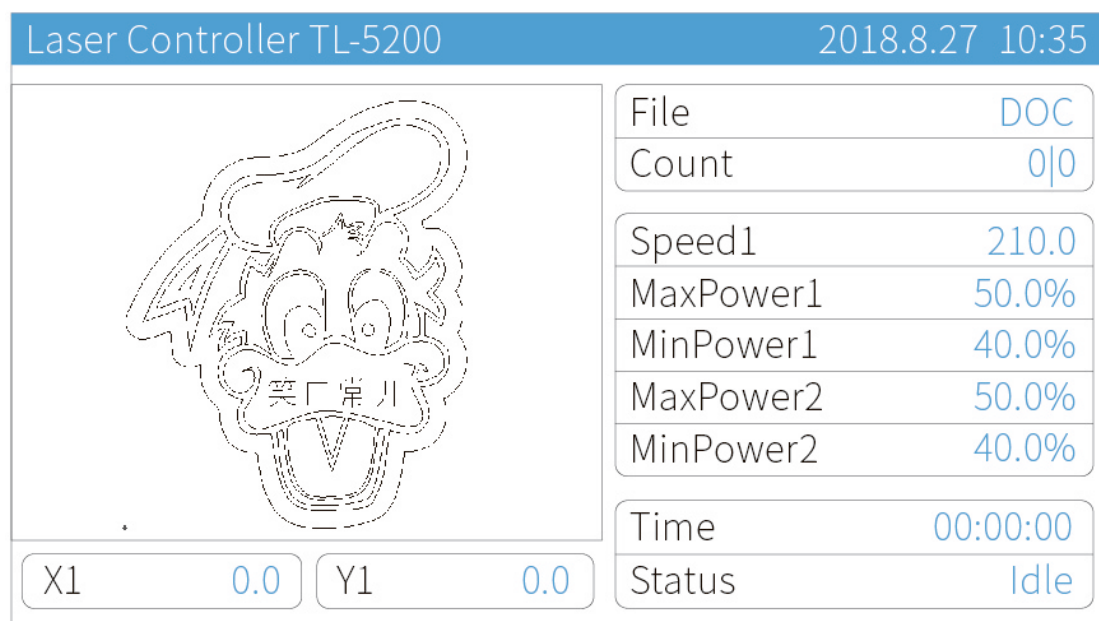
### 3.6 Hard Limit and Range

On the main page, press **【Stop】** + **【Shift】** at the same time to open the **Manufacture Params Settings** page. Then move cursor to **【HardLimit Settings】** and press **【Enter】** , users can enable or disable the hard limit parameters. TL-5200 supports range function, so users do not need to install hard limit sensors, just setting **【Range】** parameters on the relevant axis parameters page will be enough.

Set the distance per pulse of X/Y/Z/U axis according to the content of the Chapter 3.5. Then move motion axis to the maximum distance towards positive direction. You can set the coordinate value on the panel as **【Range】** .

## 4. Main Interface Preview

Figure4-1 Main Interface



Speed/Power/Time/Status:  
Work: Working parameters;  
Idle: Laser power.

Table4-1 Main Interface Introduce

Name	Instruction
Top Bar	Display the type of control card, local date and time.
Graphics	Display the graphics that has been download.
File	Display the file name currently being processed.
Count	Current counts   cumulative counts

Speed1 (mm/s)	The work speed of Laser1.
Max Power1 Min Power1 Max Power2 Min Power2	<p>Displays the Max &amp; Min power of laser 1 and 2. Max power means working power. Min power means turning power. During cutting process, if the cutting lines is uneven (different cutting depth), the maximum and minimum power of laser head should be adjusted to ensure the best cutting effect. If the maximum and minimum power is set too high, the cutting material may be damaged. If set too low, may cause incomplete cutting. Users shall set appropriate maximum and minimum power values according to different cutting materials.</p> <p>Press <b>【Shift】</b> to change the rails on the main page.</p>
Time	Displays the amount of time worked with this task.
Status	Displays the machine state. Includes working state, idle state, pause state. There will be a percentage to show the working process of the current file under working state.
X1/X2 Y1/Y2	Displays the current coordinate values in X and Y directions.


## 5. Main Page Function Introduction

### 5.1 File

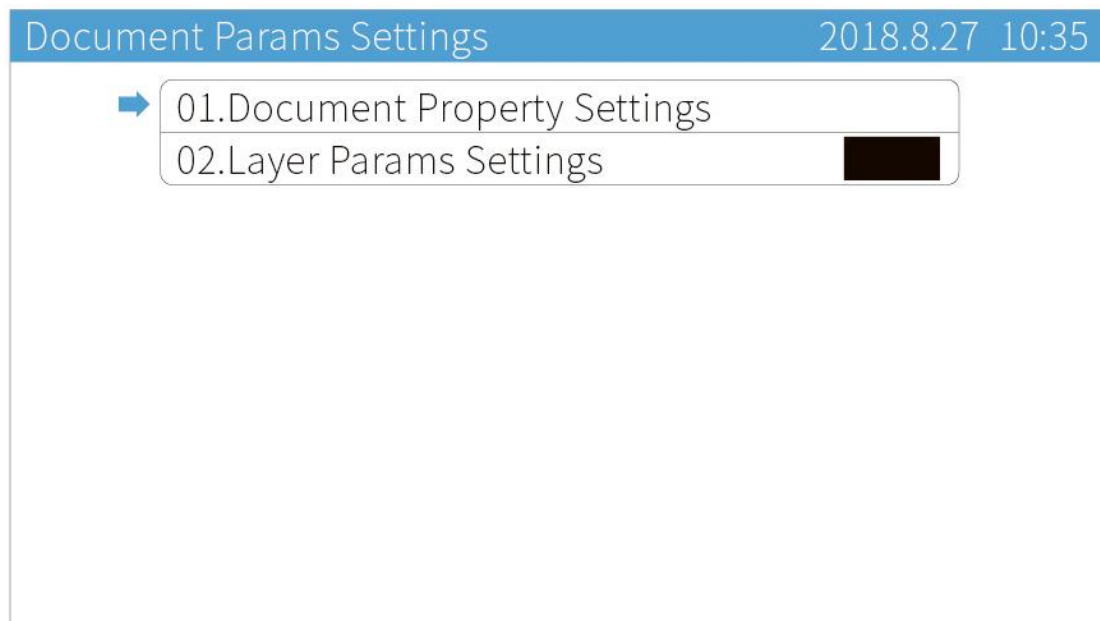
#### 5.1.1 Document Params Settings

On the main page, press **【Enter】** to make the file name highlighted as shown below. Then press **【Enter】** to open **Document Params Settings** interface.

Figure5-1-1 Select File Name

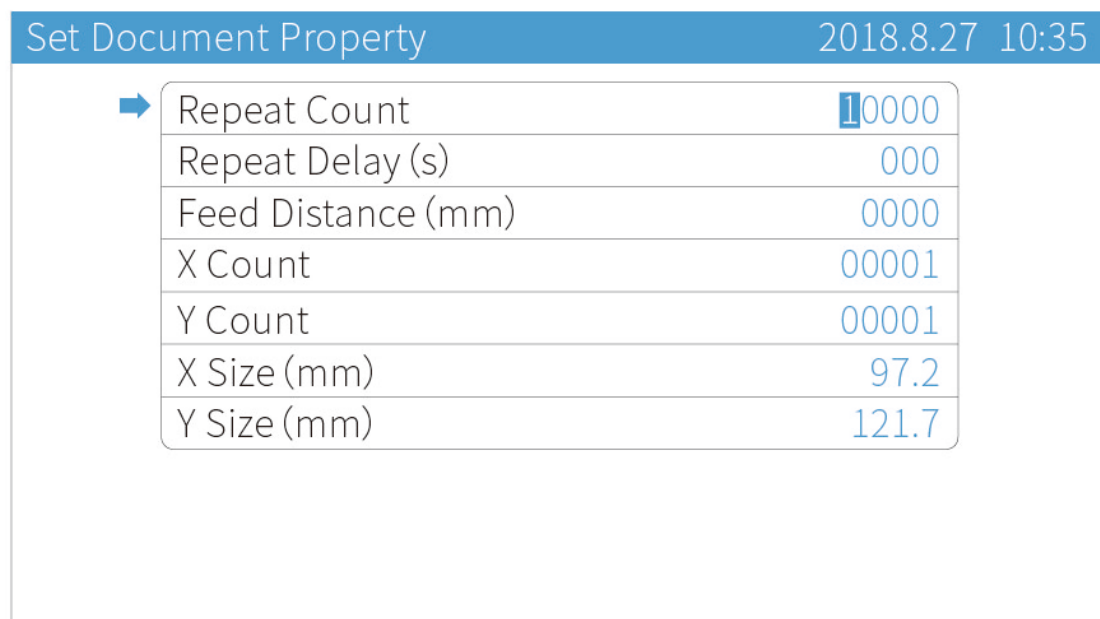
Laser Controller TL-5200		2018.8.27 10:35	
		File	DOC
		Count	0/0
		Speed(mm/s)	210.0
		MaxPower1 (%)	50.0%
		MinPower1 (%)	40.0%
		MaxPower2 (%)	50.0%
MinPower2 (%)	40.0%		
<div> <div>X1</div> <div>0.0</div> </div> <div> <div>Y1</div> <div>0.0</div> </div>		Time	00:00:00
		Status	Idle

**Figure5-1-2 Document Params Settings**



Move the cursor to **【Document Property Settings】** , press **【Enter】** . Press **【↑】【↓】【←】【→】** to move cursor, press number keys to modify parameters, and press **【Enter】** to save settings.

**Figure5-1-3 Set Document Property**



**Table5-1-1 Set Document Property Instruction**

<b>Name</b>	<b>Instruction</b>
Repeat Count	Machine repeat working times.
Repeat Delay (s)	The interval between the initial file being finished and the next one of the same.
Feed Distance (mm)	Distance of each movement of the feeding axis.
X Count	The number of graphics s processed by machine in the X direction.
Y Count	The number of graphics s processed by machine in the Y direction.
X Size (mm)	The size of graphics in X direction.
Y Size (mm)	The size of graphics in Y direction.

### 5.1.2 Layer Params Settings

On the **Document Params Settings** page, move cursor to **【Layer Params Settings】** and press **【Enter】**. On the **Layer Params Settings** page, press **【↑】【↓】【←】【→】** to move cursor, press number keys to modify parameters, press **【Enter】** to save settings.

During cutting current layer, if the cutting lines are uneven (different cutting depth), the maximum and minimum power of the laser head shall be adjusted to ensure the best cutting effect. If the maximum and minimum power is set too high, the cutting material may be damaged. If set too low, may cause incomplete cutting. Users could set appropriate maximum and minimum power values according to different cutting materials.

**Figure5-1-4 Layer Params Setting**

Layer Params Settings		2018.8.27 10:35
Work Mode	Cut	
Speed (mm/s)	0300.0	
MaxPower1 (%)	50.0	
MinPower1 (%)	40.0	
MaxPower2 (%)	50.0	
MinPower2 (%)	40.0	
MaxPower3 (%)	50.0	
MinPower3 (%)	40.0	
MaxPower4 (%)	50.0	
MinPower4 (%)	40.0	

**Table5-1-2 Layer Params Setting Instruction**


Name	Instruction
Work Mode	The mode of processing graphics.
Speed (mm/s)	The speed of processing graphics.
Max Power1 (%)	The max power of laser head1 (working power).

Min Power1 (%)	The min power of laser head1 (turning power).
Max Power2 (%)	The max power of laser head2 (working power).
Min Power2 (%)	The min power of laser head2 (turning power).
Max Power3 (%)	The max power of laser head3 (working power).
Min Power3(%)	The min power of laser head3(turning power).
Max Power4 (%)	The max power of laser head4 (working power).
Min Power24(%)	The min power of laser head4 (turning power).

## 5.2 Count

On the main page, press **【Enter】** , then move cursor to **【Count】** . Press **【Enter】** . Move cursor to **【To Clear Current count】** and press **【Enter】** to clear the current counts. Move cursor to **【To Clear Cumulative Counts】** and press **【Enter】** , the cumulative counts will change to zero.

**Figure5-2-1 Clear Total Count**

Laser Controller TL-5200		2018.8.27 10:35	
		File	DOC
		Count	00
		Speed(mm/s)	210.0
		MaxPower1 (%)	50.0%
		MinPower1 (%)	40.0%
		MaxPower2 (%)	50.0%
MinPower2 (%)	40.0%		
<div> <div>X1</div> <div>0.0</div> </div> <div> <div>Y1</div> <div>0.0</div> </div>		Time	00:00:00
		Status	Idle


**Figure5-2-2 Clear Total Count**

Laser Controller TL-5200		2018.8.27 10:35	
<div> <div>➡</div> <div> <div>To Clear Current Counts</div> <div>To Clear Cumulative Counts</div> </div> </div>			

## 5.3 Working Property

On the main page, press **【Enter】** to make the cursor highlighted and move cursor to **【Speed】** . Press **【Enter】** to open ***Set Laser Power While Idle*** page.

**Figure5-3-1 Select Speed Option**

Laser Controller TL-5200		2018.8.27 10:35	
		File	DOC
		Count	0 0
		Speed(mm/s)	210.0
		MaxPower1 (%)	50.0%
		MinPower1 (%)	40.0%
		MaxPower2 (%)	50.0%
		MinPower2 (%)	40.0%
		Time	00:00:00
		Status	Idle
		X1	0.0

Press **【↑】****【↓】****【←】****【→】** to move cursor, press number keys to modify parameters, and press **【Enter】** to save settings.

**Figure 5-3-2 Idle Laser Power Setting Page**

Set Work Property
2018.8.27 10:35

➡	Speed (mm/s)	021.0
	MaxPower1 (%)	50.0
	MinPower1 (%)	40.0
	MaxPower2 (%)	50.0
	MinPower2 (%)	40.0

**Table 5-2-1 Idle Laser Power Instruction**

Name	Instruction
Max Power1 (%)	Laser power of Laser1.
Max Power2 (%)	Laser power of Laser2.

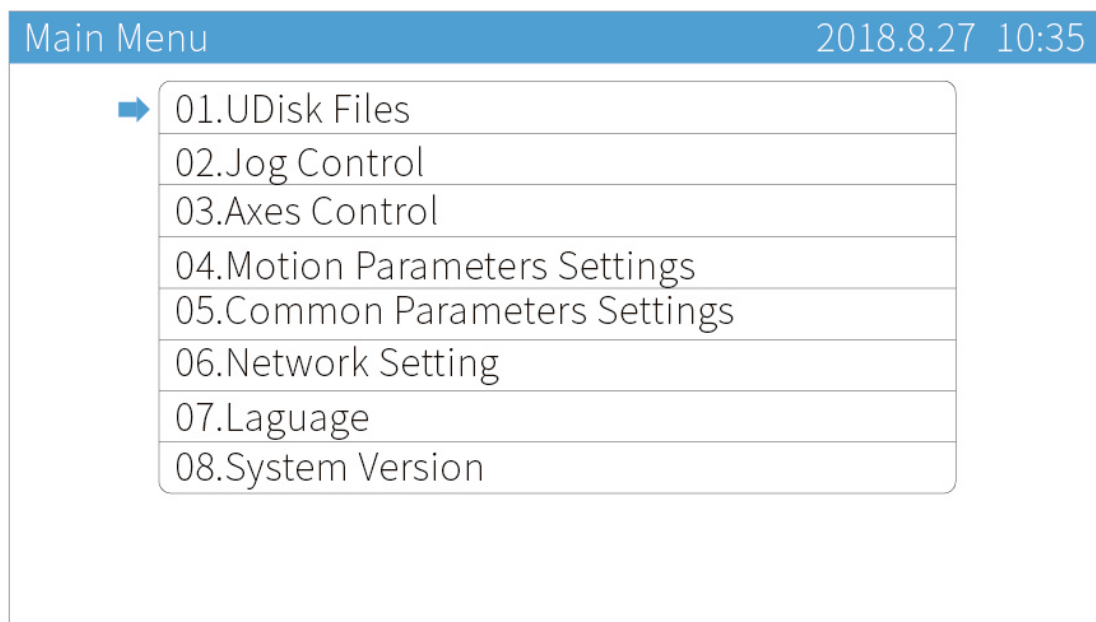
## 6. System Menu

### 6.1 U Disk Files

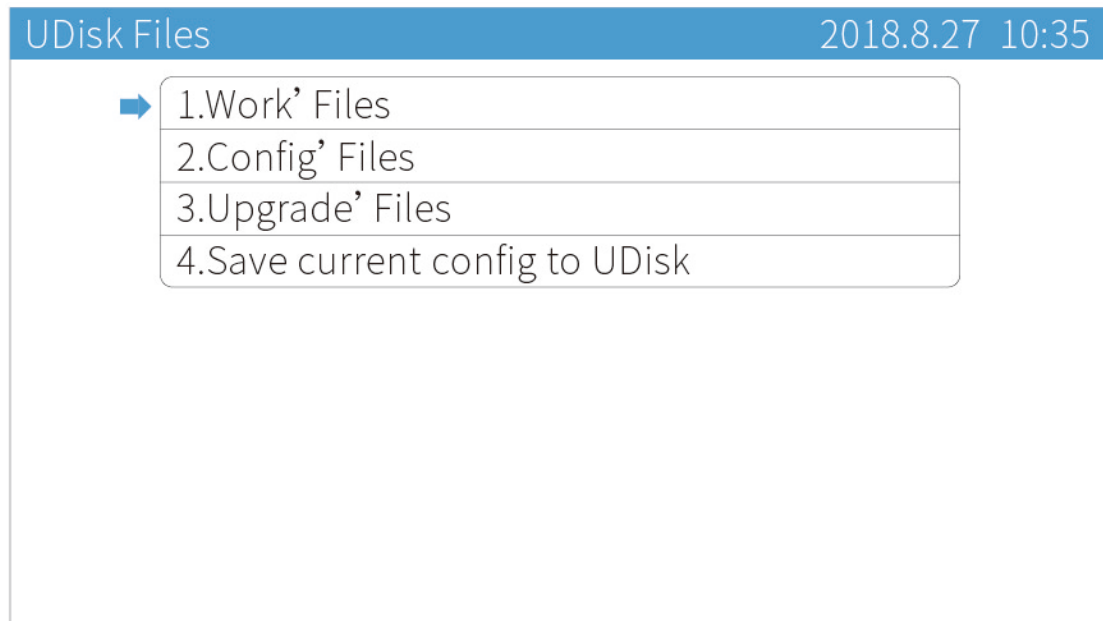
Insert a U disk into the U disk slot on the panel. If your U disk has a "light indicator" (shows connectivity) and shows that it's connected, press

**【Menu】** to enter the main menu, move the cursor to **【U Disk Files】** then press **【Enter】** to enter U disk files management.

**Figure6-1-1 Main Menu Interface**



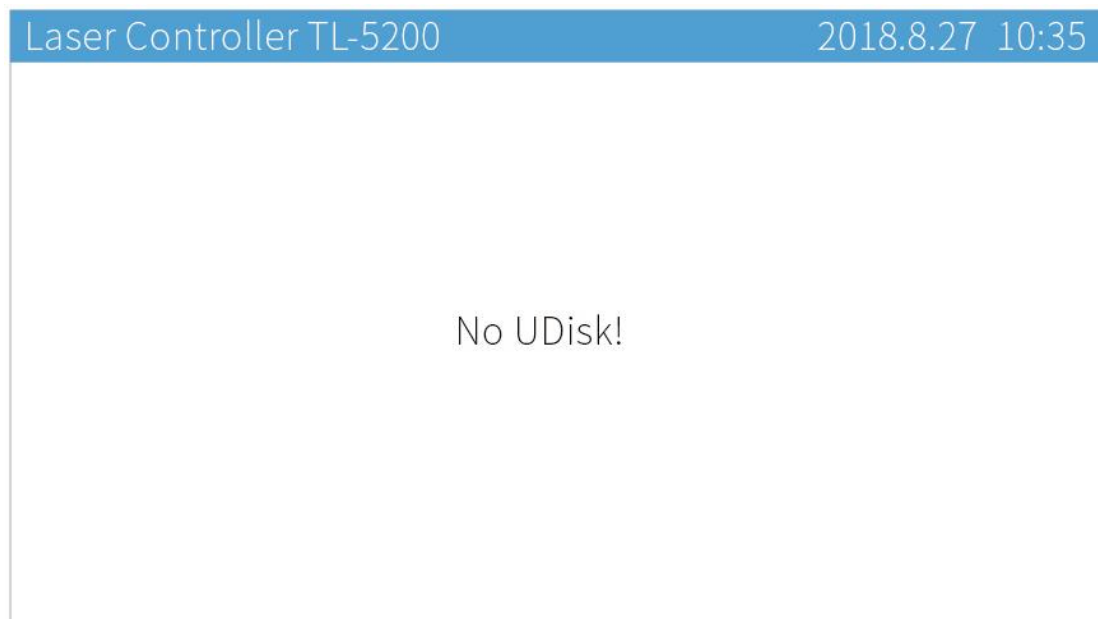
**Figure6-1-2 U Disk Files**



- ① The U disk must be formatted to FAT32 File system in advance. Quick Format is forbidden. Any other files formations are not supported.
- ② Recommend using a U disk with a "light indicator" to ensure if the U disk is connected successfully with the main board
- ③ When the U disk has never been able to read, try using a different U disk.
- ④ The U disk can't be used to install system.

If the U disk can't be read, you will see the interface below.

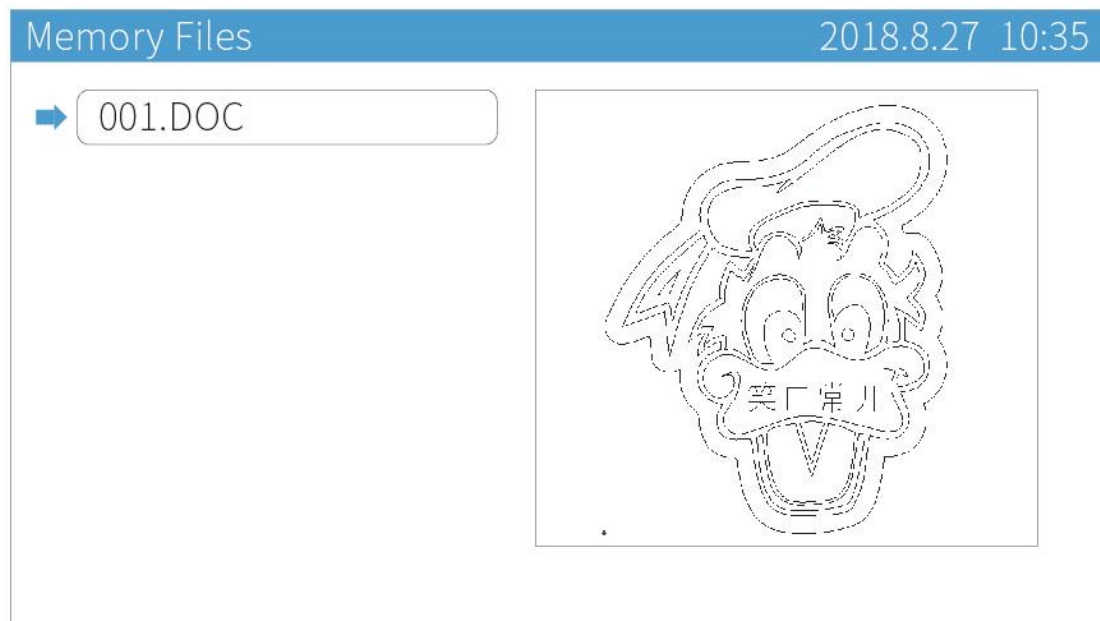
**Figure6-1-3 No U Disk Interface**



### 6.1.1 Work Files

Move the cursor to **【Work Files】** and press **【Enter】**. On the panel, the working file in the U disk will be presented. The right side shows the working file previewing. Press **【↑】** **【↓】** to move cursor and press **【Enter】** to copy the working file from U disk to mainboard storage.

**Figure6-1-4 U Disk Work Files List**

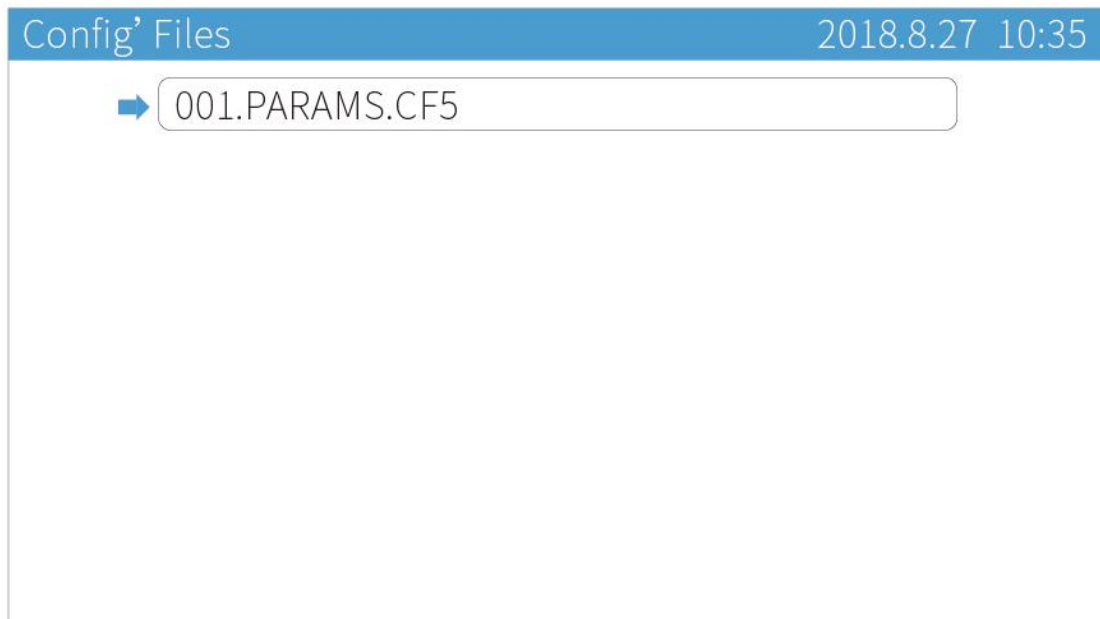


The working file in the U disk is saved with a suffix of UD5. Files other than the ".UD5" file extension will not be readable.

### 6.1.2 Config Files

Move cursor to **【Config File】** and press **【Enter】**. Move cursor to the file which you need to copy to main board. Then Press **【Enter】** to save current config file to mainboard.

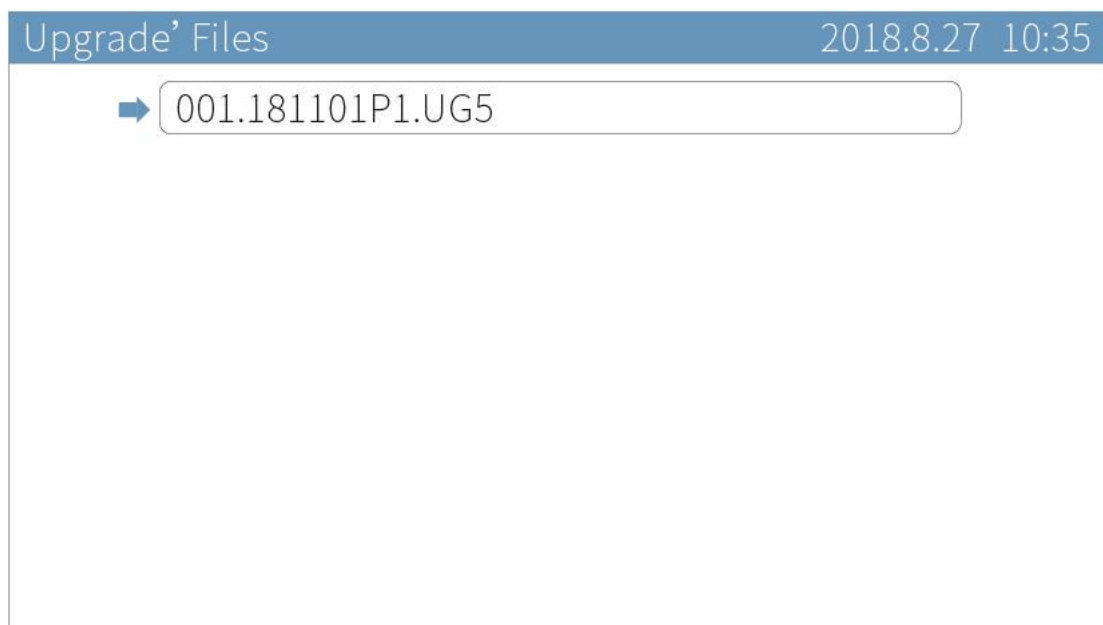
**Figure6-1-5 Config Files List**



### 6.1.3 Upgrade Files

Move cursor to **【Upgrade Files】** and press **【Enter】** . Move the cursor to the file you need, press **【Enter】** then it will start the upgrading process.

**Figure6-1-6 Upgrade Files**



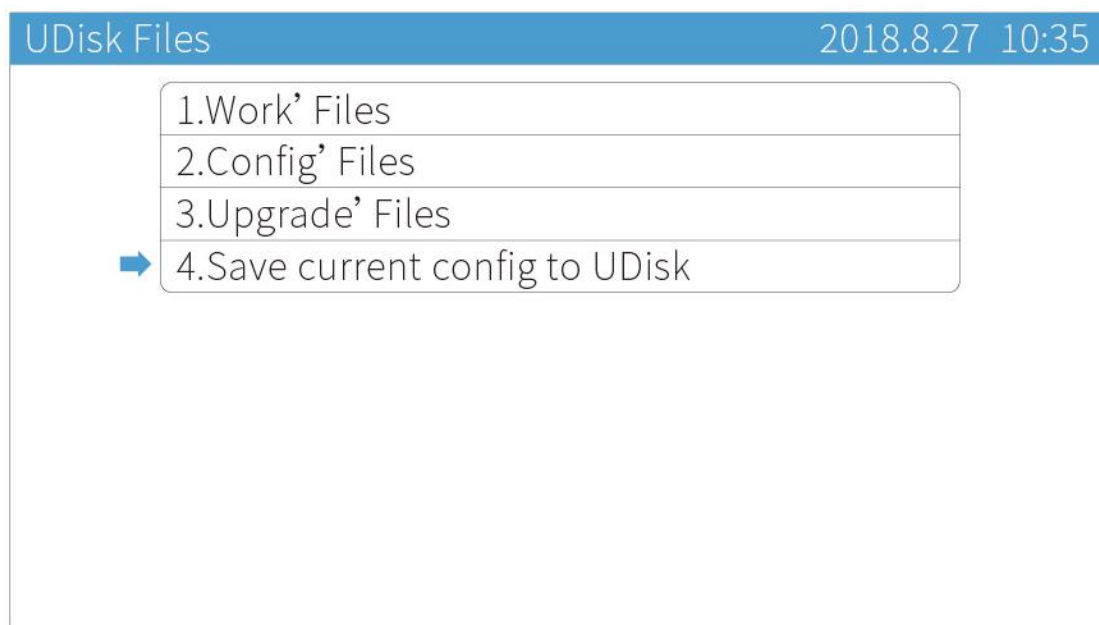


Don't turn off the power during upgrade, otherwise it will cause damage to the mainboard. The upgrade will take about 30s. After finishing upgrade, the mainboard will reset automatically.

#### 6.1.4 Save Current Config to U Disk

Move cursor to **【Save Current Config to U Disk】** and press **【Enter】** to save current mainboard config file to the U disk. And the file will be named as "Params.CF5" in the U disk.

**Figure6-1-7 Save Current Config to U Disk**



## 6.2 Jog Control

On the main page, press **【Menu】**, move cursor to **【Jog Control】** and press **【Enter】** to enter ***Jog Control*** page. Then press number keys to modify

the distance. Do not set too large **【Jog Distance】** , please make sure it within the working range.

On the **Jog Control** page, press number keys to modify the jog distance, press **【Z ↑】【Z ↓】** to move cursor, press **【↑】【↓】【←】【→】** to make motion axis jog.

The jog control can move axis accurately and adjust the distance per pulse of axis. [Please check the Chapter 3.5 to know more about distance per pulse.](#)

**Figure 6-2-1 Jog Control Interface**

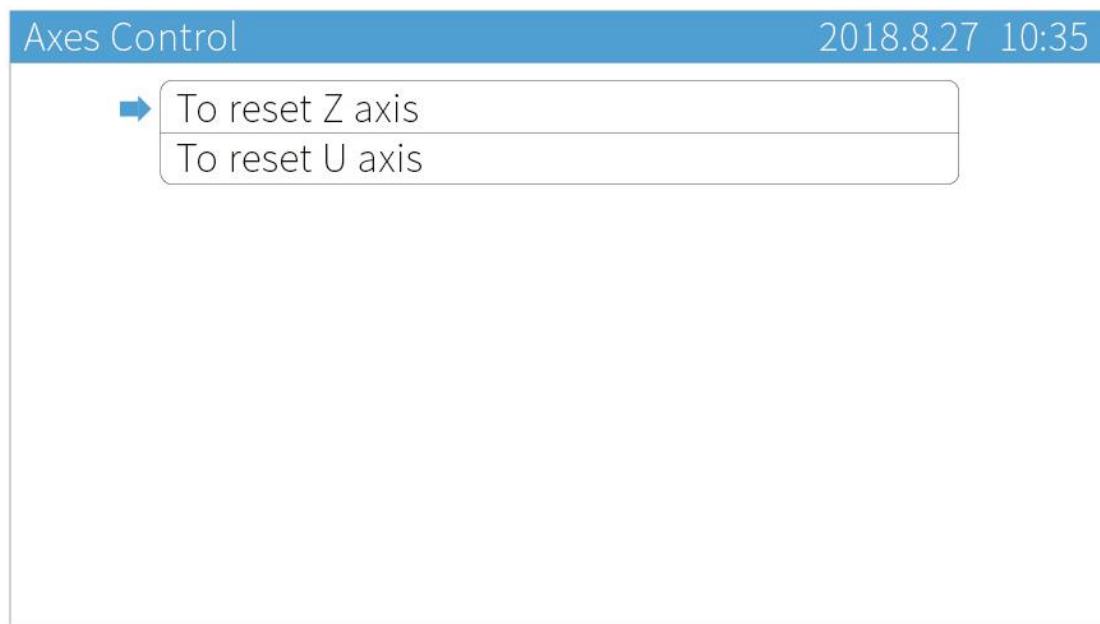
Jog Control		2018.8.27 10:35
➡	Jog Distance (mm)	00000.5
	XY Jog	
	Z Jog	
	U Jog	

## 6.3 Axes Control

On the main page, press **【Menu】** and move cursor to **【Axes Control】** , press **【Enter】** to enter **Axes Control** page. Press **【↑】【↓】** to move cursor, and press **【Enter】** to make axis reset.

The Z axis can be used as the lifting shaft, platform lifting shaft and multi-head shifting shaft. When the Z axis is reset, the Z axis will stop at the limiter position.

**Figure 6-3-1 Axes Control Interface**



## 6.4 Motion Parameters Settings


On the main page, press **【Menu】** and move cursor to **【Motion Parameters Settings】**, press **【Enter】** to enter ***Motion Parameters Settings*** page. Press **【↑】****【↓】** to move cursor and press number keys to modify parameters, press **【Enter】** to save settings.

**Figure 6-6-1 Motion Parameters Settings Interface**

Motion Parameters Settings		2018.8.27 10:35
➡	Space Speed (mm/s)	0300.0
	Cut Jerk (10000mm/s <sup>3</sup> )	06.0
	Space Jerk (10000mm/s <sup>3</sup> )	10.0
	Min Acc (mm/s <sup>2</sup> )	300
	Engrave Acc (mm/s <sup>2</sup> )	10000
	Start Speed (mm/s)	10.0
	Speed Factor	3.0

The settings of these parameter items will affect the cutting effect, please adjust according to your requirements.

**Table 6-6-1 Motion Parameters Instruction**

	Name	Instruction
	Space Speed (mm/s)	The movement speed of laser head when there is no laser output.
	Cut Jerk (mm/s <sup>3</sup> )	The variation of cutting acc increases or decreases in unit of 10 thousand each time.
	Space Jerk (mm/s <sup>3</sup> )	The variation of movement acc when there is no laser output and it increases or decreases in unit of 10 thousand each time.
	Min Acc	The acceleration of laser head when it turns and

	(mm/s <sup>2</sup> )	this value increases or decreases in unit of 50 or 100 each time.
	Engrave Acc (mm/s <sup>2</sup> )	The variation of engraving speed and it is only effective to engrave.
	Start Speed (mm/s)	The initial speed of laser head from rest to motion.
	Speed Factor	Parameter changes throughout the system. We suggest that lower speed is going to be filled in with 0.5 or 1, while regular speed with 2 and high speed with 3 or 4. This option should be filled in with 0.05 when cutting acrylic or wood. It also has an impact on smoothness when turning.

During cutting process, if the actual cutting speed is far less than the working speed users have set, it indicates that the **【Cut Jerk】** is set too small, so that the laser head cannot reach the set working speed quickly. If the actual cutting speed is relatively fast, the cutting line will jitter, this case indicates that the **【Cut Jerk】** is set too high and the parameter value should be reduced. In the same way, if the **【Space Jerk】** is set too small, the speed of laser head will not reach the set speed when there is no laser output. If the parameter is set too large, the initial position of cutting (after the laser head moving without laser) will jitter.

The start speed is the initial speed of the laser head from rest to start movement. If the cutting line is too thick at the initial position of cutting, it indicates that the parameter value is too small. If the line jitters at the initial position of cutting, this parameter value is set too large.

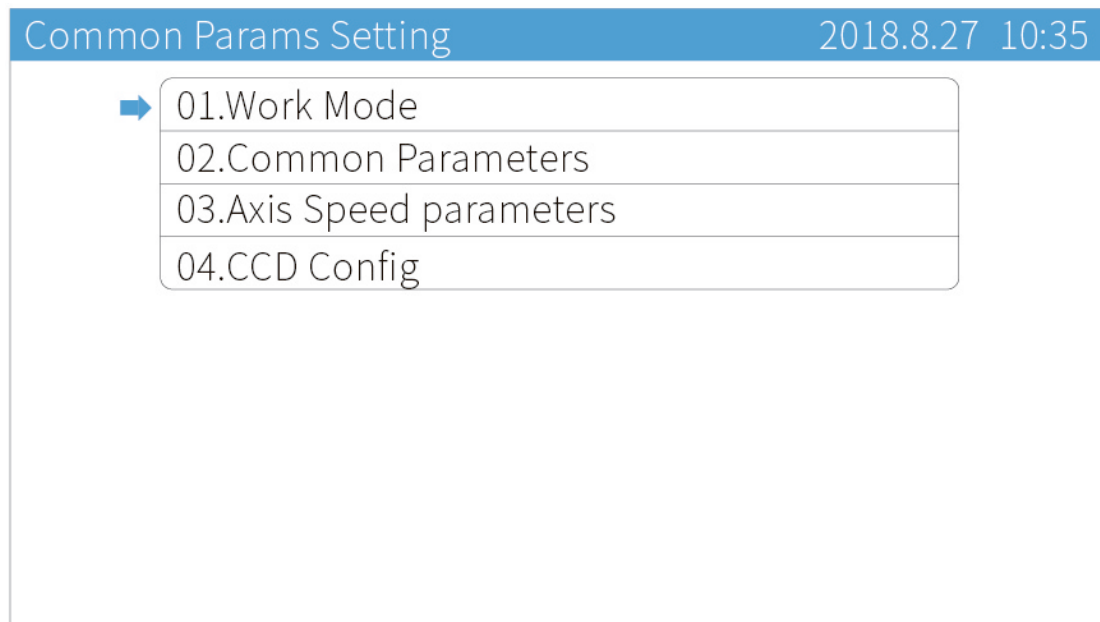
The speed factor controls the speed of turning during cutting. If the cutting line is too thick when turning, the parameter is too small. If the cutting line is too thin when turning and the graphics cannot be cut completely, this case indicates that this parameter value is set too large, users should set a smaller value.

The **【Engrave ACC】** is the change rate of speed during engraving. This parameter is only valid during engraving. During the engraving process, if the space distance of laser head is too large, then the **【Engrave ACC】** is set too small and should be adjusted appropriately. If the space distance of laser head is too small and the edge of graphics is not carved completely, it indicates that the **【Engrave ACC】** is set too large and should be reduced appropriately.

## 6.5 Common Parameters Settings

On the main page, press 【Menu】 and move cursor to 【Common Parameters Settings】, press 【Enter】.

Figure 6-5 Common Parameters Settings Interface



### 6.5.1 Work Mode

On the **Common Params Settings** page, move cursor to 【Work Mode】 and press 【Enter】. Press 【↑】【↓】 to move cursor, press 【←】【→】 to modify options and press 【Enter】 to save settings.

**Figure6-5-1 Common Parameters Settings Interface**

Work Mode		2018.8.27 10:35
➡	Go Origin After Reset	Enable
	Origin Mode	Key Origin
	GoBack Position	Current Origin
	Count Mode	Count per work
	Feeding Delay Mode	Delay After Feeding

**Table6-5-1 Work Mode Instruction**

Name	Instruction
Go Origin After Reset	<p><b>Enable:</b> the laser head will be back to Origin after resetting.</p> <p><b>Disable:</b> the laser head will stay at the machine origin point (zero point) after reset.</p>
Origin Mode	<p><b>Current Position:</b> keep the current position of laser head and set this position as origin point to start cutting.</p> <p><b>Key Origin:</b> press panel 【Origin】 button after the laser head moved to the chosen position.</p> <p><b>Soft Origin:</b> set the origin point when drawing a file on LaserCAD software.</p> <p><b>Machine Zero As Origin:</b> set the machine zero point as origin point.</p>

Go Back Position	<p><b>Current Position:</b> laser head will stay at where task finished.</p> <p><b>Current Origin:</b> go back to Origin point after finishing work.</p> <p><b>Zero Coord:</b> laser head goes back to machine zero point since all finished.</p>
Count Mode	<p><b>Count per work:</b> it will be counted as once after all files cut.</p> <p><b>Count per Light:</b> it will be counted as once after laser optical output one time.</p> <p><b>Single of Array:</b> it will be counted as once after the solid graphics in the file is cut.</p>
Feeding Delay Mode	<p><b>Delay after feeding:</b> the period between finishing cutting and feeding.</p> <p><b>Delay before feeding:</b> the period between feeding and starting to cut.</p>

### 6.5.2 Common Parameters

On the **Common Params Settings** page, move cursor to **【 Common Parameters】** and press **【Enter】** . Press **【 ↑ 】【 ↓ 】** to move cursor and press number keys to modify parameters, press **【Enter】** to save settings.

**Figure 6-5-2 Common Parameters Interface**

Common Parameters		2018.8.27 10:35
➡	AutoFocus Distance (mm)	00.0
	KeyMove' Speed (mm/s)	100.0
	RunBox' Speed (mm/s)	200.0
	CutBox' Speed (mm/s)	050.0
	Blow Open Delay (s)	0.00
	Blow Close Delay (s)	0.00

**Table 6-5-2 Common Parameters Instruction**

Name	Instruction
Auto Focus Distance (mm)	The distance between the laser head and working platform.
Key Move Speed (mm/s)	The motion speed of axis when press the direction keys on panel.
Run Box Speed (mm/s)	The speed at which the laser head runs along the outer frame of graphics without laser output.
Cut Box Speed (mm/s)	The speed at which the laser head cuts along the outer frame of graphics.
Blow Open Delay(s)	The period between laser head optical output and air blowing started.

Blow Close Delay(s)	The period between laser head optical output stopped and air blowing stopped.
---------------------	---

### 6.5.3 Axis Speed Parameters

On the **Common Params Settings** page, move cursor to **Axis Speed Parameters** and press **Enter**. Press **↑** **↓** to move cursor and press number keys to modify parameters, press **Enter** to save settings.

Figure 6-5-3 Axis Speed Parameters Interface

Axis Speed parameters		2018.8.27 10:35
➡	Z Work Speed (mm/s)	080.0
	U Work Speed (mm/s)	200.0
	XY Home Speed (mm/s)	050.0
	Z Home Speed (mm/s)	040.0
	U Home Speed (mm/s)	050.0

Table 6-5-3 Axis Speed Parameters Instruction

Name	Instruction
Z Work Speed (mm/s)	The work speed of Z axis.

U Work Speed (mm/s)	The work speed of U axis.
XY Home Speed (mm/s)	The reset speed of XY axis.
Z Home Speed (mm/s)	The reset speed of Z axis.
U Home Speed (mm/s)	The reset speed of U axis.

#### 6.7.4 CCD Config

On the **Common Params Settings** page, move cursor to **【CCD Config】** and press **【Enter】**. Press **【↑】****【↓】** to move cursor, press **【←】****【→】** to modify options and press **【Enter】** to save settings.

Figure6-5-4 CCD Config

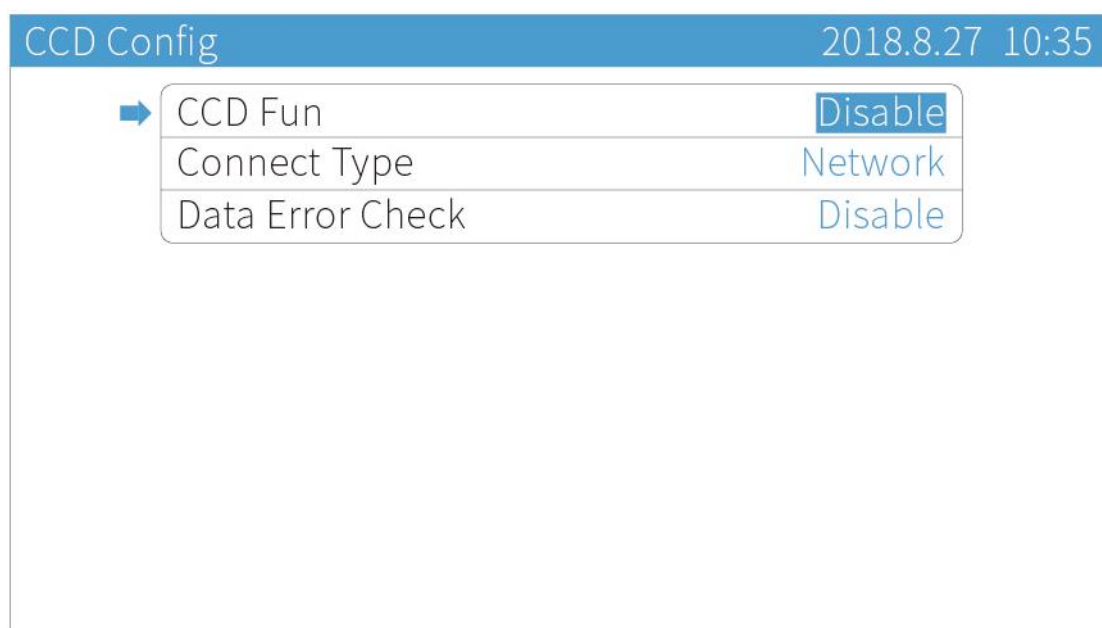


Table6-5-4 CCD Config Instruction

Name	Instruction
CCD Fun	The switch of CCD function.
Connect Type	Set USB or network connection type.
Data Error Check	Check if the Mark points in the file loaded are the same with camera.

## 6.6 Network Settings

On the main page, press **【Menu】**, move cursor to **【Network Settings】** and press **【Enter】**. Press **【↑】****【↓】** to move cursor, press number keys to modify parameters and press **【Enter】** to save settings.

**Figure6-6-1 Network Settings**

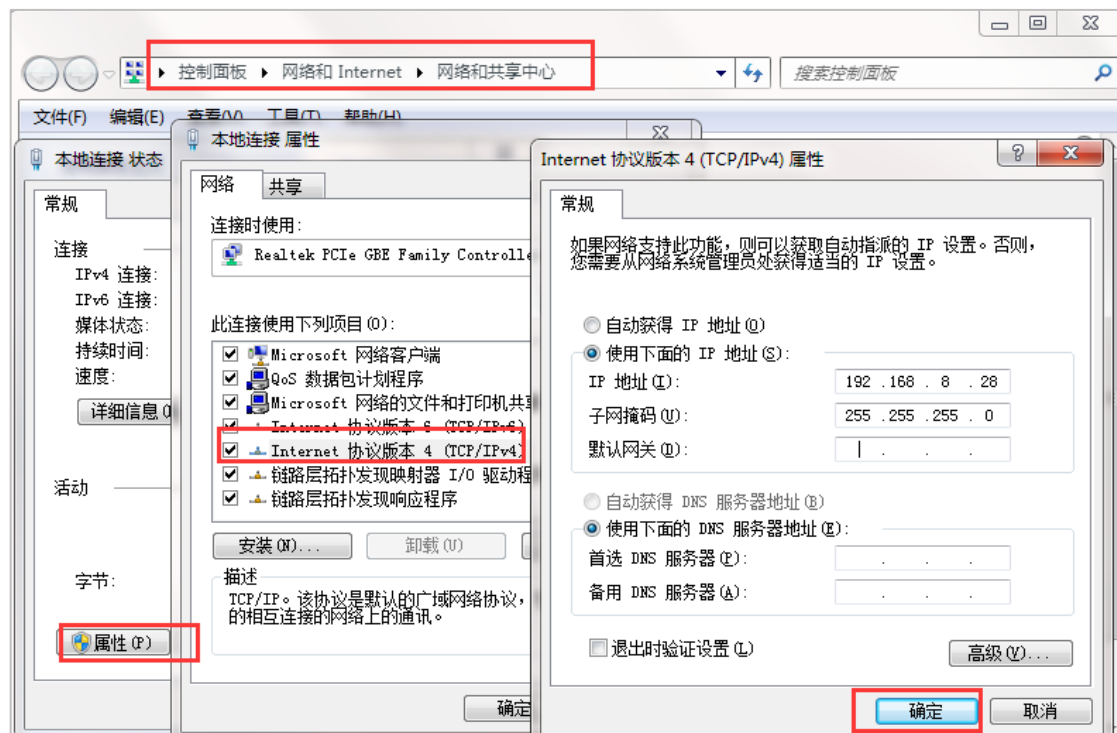
Network Setting		2018.8.27 10:35
➡ IP Part1		192
IP Part2		168
IP Part3		008
IP Part4		008

The default IP address of mainboard is 192.168.8.8. When connecting the main board and PC terminal through network cable, the computer IP should be modified to make the computer IP address and IP address of the main board in the same network segment. For example, the computer IP address can be set to 192.168.8.28.

Based on the Windows7 system, users can modify the native IP address in the following ways. First, open the Control Panel, select Network and Internet options, and click View Network Status and Tasks. Then, double-click the Local Connection, click the Property button, and double-click the

TCP/IPv4 option to open the IP address modification interface. Finally, input the corresponding IP address, click OK button to save, other parameters do not need to fill in.

**Figure6-6-2 Modify IP Address**



## 6.7 Language

On the main page, press **【Menu】** and move cursor to **【Language】**, press **【Enter】**. Press **【←】** **【→】** to change language and press **【Enter】** to save settings. TL-5200 now supports 3 kinds of languages, Simplified Chinese, English and Portuguese.

Figure 6-9-1 Language Interface



## 6.8 System Version

On the main page, press **【Menu】** and move cursor to **【System Version】**, press **【Enter】** to see the system information.

If the encryption or decryption of the mainboard is successful, the product ID will change.

**Figure 6-8-1 System Version Interface**

System Version		2018.8.27 10:35
Product Name	TL-5200	
Product ID	0E00A026 00000000	
Version	2.18.9.10	
➡ User authorization code		

Move cursor to **【User authorization code】** and press **【Enter】**. Press **【↑】** **【↓】** to move cursor, press number keys to modify parameters and press **【Enter】** to save settings.

The user authorization code is used for encryption or decryption. If you don't need encryption, there is no need to modify it. If you need encryption, please see the detail in encryption manual.

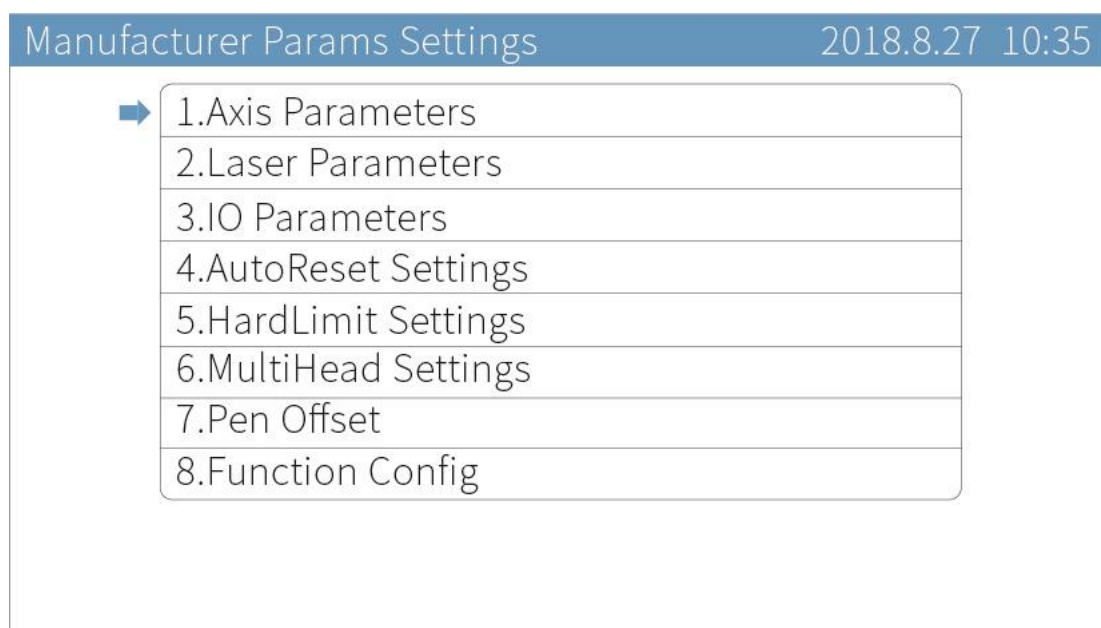
**Figure 6-8-2 User Authorization Code Interface**

User authorization code		2018.8.27 10:35
➡	Code 1	100000
	Code 2	100000
	Code 3	100000

## 7. Manufacture Params Settings

On the main page, press **【 Stop 】** + **【 Shift 】** together, you will see ***Manufacture Params Settings*** page.

**Figure7-1 Manufacture Params Interface**



### 7.1 Axis Parameters

Move cursor to **【 Axis Parameters 】** and press **【 Enter 】** . Take the X axis parameter setting as an example, other axis parameter settings are the same.

**Figure7-1-1 Axis Parameters Interface**

Axis Parameters		2018.8.27 10:35
➡	1.X Axis Parameters	
	2.Y Axis Parameters	
	3.Z Axis Parameters	
	4.U Axis Parameters	

On the **X Axis Parameters** page, press **【↑】** **【↓】** to move cursor, press **【←】** **【→】** to modify options, press number keys to modify parameters and press **【Enter】** to save settings.

**Figure7-1-2 X Axis Parameters Interface**

X Axis Parameters		2018.8.27 10:35
➡	Distance Per Pulse (um) ...	06.500000
	Valid Pulse Edge	Failling Edge
	Datum Direction	Negative
	Key Direction	Negative
	Limit Polarity	Negative
	Range (mm)	00500
	Start Speed (mm/s)	15.0
	Max Acc (mm/s <sup>2</sup> )	10000
	Max Speed (mm/s)	0500.0
	X2 Distance Per Pulse(um)...	06.500000

Move cursor to **【Distance Per Pulse】** , press **【Enter】** to enter the **To**

**Calculate the Pulse Distance** page. Press 【 ↑ 】 【 ↓ 】 to move cursor, press number keys to modify parameters, and press 【Enter】 to calculate the distance per pulse. [The calculation of distance per pulse, please refer to the Chapter 3.5 for more details.](#)

**Figure7-1-3 Calculate the Distance Per Pulse**

To Calculate the pulse Distance		2018.8.27 10:35
➡	Expected Length (mm)	0200.00
	Actual Length (mm)	0200.00

**Table7-1-1 X Axis Parameters Instruction**

Name	Instruction
Distance Per Pulse (um)	The single distance or angle which the motor moves, when the controller sends a pulse signal. If set incorrectly, the graphics will change. The distance per pulse of X1 axis.
Valid Pulse Edge	Effective values for driver level to change, Falling Edge or Rising Edge.
Datum Direction	The direction in which the machine moves when reset. If set incorrectly, the axis moves against origin direction.
Key Direction	The direction in which the axis moves when press keys on

	the panel. When set incorrectly, the axis moves opposite direction.
Limit Polarity	The control level that limit switch passes to the control panel. When set incorrectly, the limit will fail. If the limit sensor is NPN, the limit polarity is negative. If the limit sensor is PNP, the limit polarity is positive.
Range(mm)	The working range of machine.
Start Speed (mm/s)	The initial speed at which the axis moves from rest to motion.
Max ACC (mm/s <sup>2</sup> )	The maximum acceleration value of the motion axis when the axis increases or decreases speed.
Max Speed (mm/s)	The maximum speed which the motion axis supports.
X2 Distance Per Pulse(um)	The distance per pulse of X2 axis.

## 7.2 Laser Parameters

On the **Manufacture Params Settings** page, move cursor to **【Laser Parameters】** and press **【Enter】**. Press **【↑】****【↓】** to move cursor, press **【←】****【→】** to modify options, press number keys to modify parameters and press **【Enter】** to save settings.

**Figure7-2-1 Laser Parameters Interface**

Laser Parameters		2018.8.27 10:35
➡	Laser Mode	CO2 Glass Tube
	TTL Valid Level	Low Level
	PWM Frequency (hz)	20000
	Max Power (%)	98
	RF Min Power (%)	0.0
	Laser1 Water Protect	Disable
	Laser2 Water Protect	Disable
	Laser3 Water Protect	Disable
	Laser4 Water Protect	Disable

**Table7-2-1 Laser Parameters Instruction**

Name	Instruction
Laser Mode	Laser tube type: CO2 Glass Tube, RF tube.
TTL Valid Level	The control level of laser tube.
PWM Frequency (Hz)	Set the pulse frequency of control signal used by laser.
Max Power (%)	The maximum power of laser tube. The maximum power

	value set by user can't be higher than this value and the laser power is displayed as a percentage.
RF Min Power (%)	Turning power.
Laser1 Water Protect	Water protection switch. If enable this function, the machine will stop working when the machine detects the signal of water stopping.
Laser2 Water Protect	Water protection switch. If enable this function, the machine will stop working when the machine detects the signal of water stopping.
Laser3 Water Protect	Water protection switch. If enable this function, the machine will stop working when the machine detects the signal of water stopping.
Laser4 Water Protect	Water protection switch. If enable this function, the machine will stop working when the machine detects the signal of water stopping.

## 7.3 I/O Parameters

On the **Manufacture Params Settings** page, move cursor to **【 IO Parameters 】** and press **【 Enter 】** . Press **【 ↑ 】【 ↓ 】** to move cursor, press **【 ← 】【 → 】** to modify options and press **【 Enter 】** to save settings.

If want to use feed function, users should enable **【Feed Switch】** on this page.

**Figure7-3-1 I/O Parameters Interface**

The screenshot shows a web interface titled "IO Parameters" with a timestamp "2018.8.27 10:35". Below the title is a table with four rows. Each row has a blue arrow icon to its left. The parameters and their values are: Foot Switch (Disable), Open Protection (Disable), Feed Switch (Disable), and Input Valid Level (Low Level).

Parameter	Value
Foot Switch	Disable
Open Protection	Disable
Feed Switch	Disable
Input Valid Level	Low Level

**Table7-3-1 I/O Parameters Instruction**

Name	Instruction
Foot Switch	Enable or disable the foot switch function.
Open Protection	Enable or disable the open protection function.
Feed Switch	Enable or disable the feed function.
Input Valid Level	Set input IO to low level or high level.

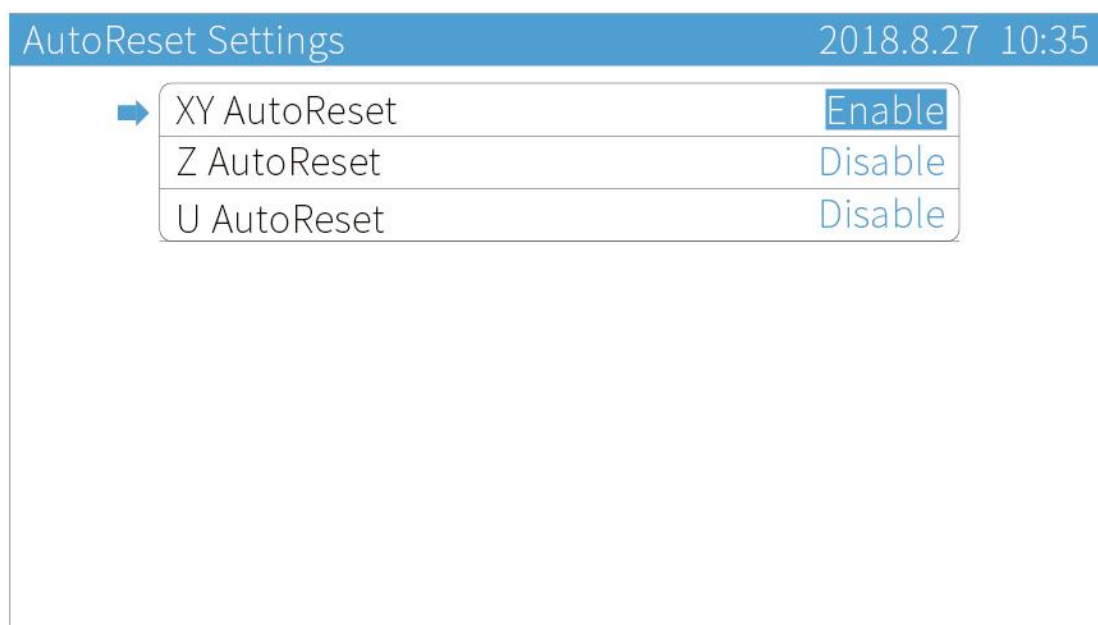
## 7.4 Auto Reset Settings

On the **Manufacture Params Settings** page, move cursor to **Auto Reset Settings** and press **Enter**. Press **↑** **↓** to move cursor, press **←**

**→** to modify options and press **Enter** to save settings.

In general, we suggest users to enable axis AutoReset function, and disable the feeding axis AutoReset.

**Figure7-4-1 Auto Reset Setting Interface**



**Table7-4-1 Auto Reset Settings Instruction**

Name	Instruction
XY Auto Reset	If enable this function, when power on or reset the machine, the XY axis will reset to origin point.
Z Auto Reset	If enable this function, when power on or reset the machine, the Z axis will reset to origin point.

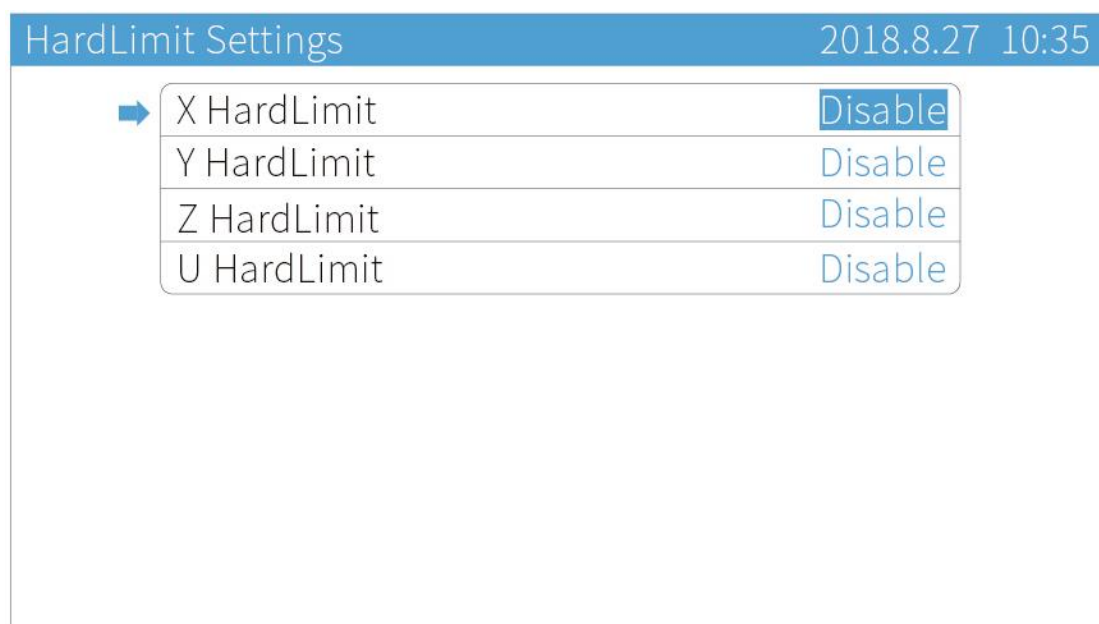
U Auto Reset	If enable this function, when power on or reset the machine, the U axis will reset to origin point.
--------------	---

## 7.5 HardLimit Settings

On the **Manufacture Params Settings** page, move cursor to **HardLimit Settings** and press **Enter**. Press **↑** **↓** to move cursor, press **←** **→** to modify options and press **Enter** to save settings.

TL-5200 supports working range limit, users do not need to install hard limiter in general, just set the **Range** on the axis parameters page.

Figure7-5-1 HardLimit Setting Interface



**Table7-5-1 Auto Reset Settings Instruction**

Name	Instruction
X HardLimit	HardLimit switch of X axis. If use HardLimit, enable the function here.
Y HardLimit	HardLimit switch of Y axis. If use HardLimit, enable the function here.
Z HardLimit	HardLimit switch of Z axis. If use HardLimit, enable the function here.
U HardLimit	HardLimit switch of U axis. If use HardLimit, enable the function here.

## 7.6 MultiHead Settings

On the **Manufacture Params Settings** page, move cursor to **MultiHead Settings** and press **Enter**. Press **↑** **↓** to move cursor, press **←**

**→** to modify options, press number keys to modify parameters and press **Enter** to save settings.

**Figure7-6-1 MultiHead Interface**

MultiHead Settings
2018.8.27 10:35

➡

Head Count
1

Z1X1 Head Space (mm) 0120.0

Z2X2 Head Space (mm) 0000.0

**Table7-6-1MultiHead Instruction**

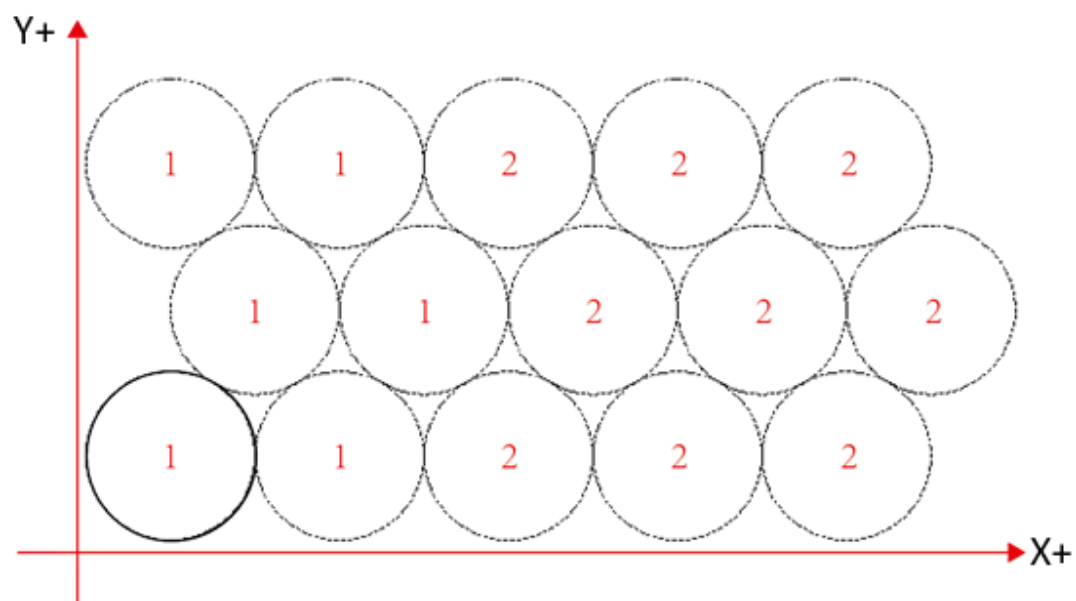
Name	Instruction
Head Count	Set the head count, “1” or “2” or “3” or “4” for TL-5200.
Z1 X1 Head Space (mm)	The distance between Z1 and X1.
Z2 X2 Head Space (mm)	The distance between Z2 and X2.

When the machine is basic double rails, input “1” into **【Head Count】** , when the machine is double heads moving separately, input “2” into the **【Head Count】** . If the machine works under double heads moving separately mode, users need to do some settings as follow.

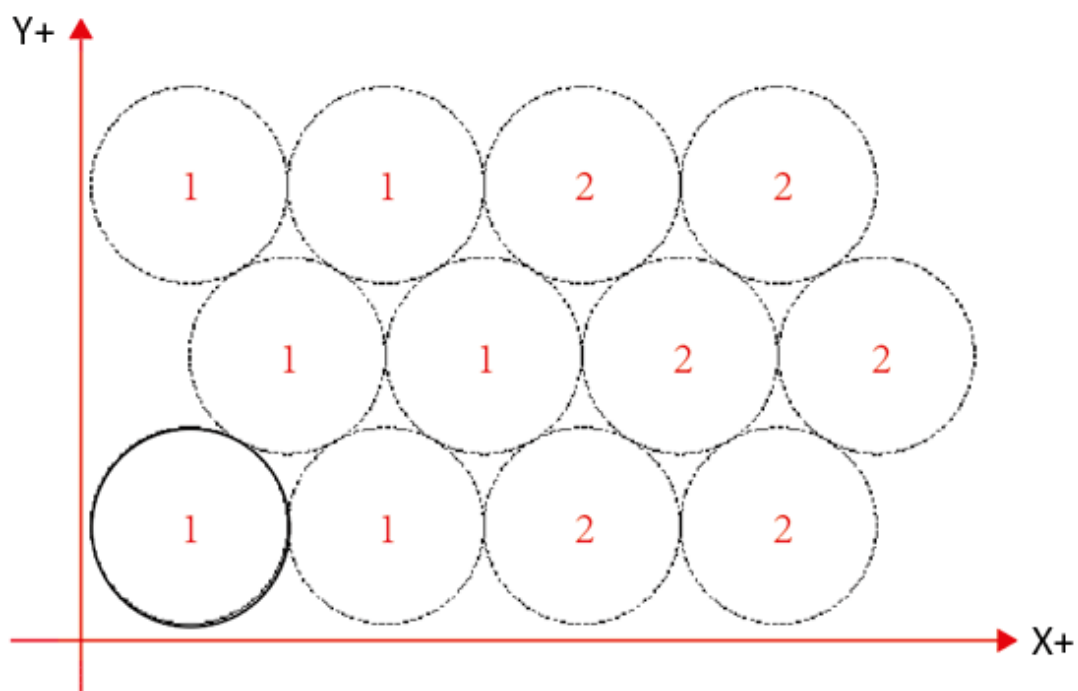
1. Enable **【Z AutoReset】** function, and set **【Head Count】** to “2”.

2. Reset the machine, make Laser head1 and Laser head2 on the Rail 1 laser by press **【Laser】** on the panel, and mark these two points, then measure the distance between these points, the distance is the **【Z1 X1 Head Space】** .
3. Reset the machine, make Laser head1 and Laser head2 on the Rail 2 laser by press **【Laser】** on the panel, and mark these two points, then measure the distance between these points, the distance is the **【Z2 X2 Head Space】** .
4. Enter the **Z Axis Parameters** page, and set the distance per pulse of Z axis. [Please refer to the Chapter 3.5 to know more about the calculation.](#)
5. When multi-head cutting, the graphics in LaserCAD are dashed. If the graphics are solid lines, the Laser head1 (main laser head) will cut all the file, and the Laser head2 won't cut. If the number of graphics in single lines is odd, the system defaults to cutting even numbers of graphics with laser head1 and odd numbers of graphics with laser head2, like Figure 7-6-4. If the number of graphics in single line is even, the system defaults to cutting the same number of laser heads 1 and 2, as shown in Figure 7-6-5.

**Figure7-6-4 The Odd Number of Graphics**



**Figure7-6-5 The Even Number of Graphics**



## 7.7 Pen Offset

On the **Manufacture Params Settings** page, move cursor to **Pen Offset** and press **Enter** . Press **←** **→** to modify options, press number keys to modify parameters and press **Enter** to save settings.

Figure7-7-1 Function Config Interface

Pen Offset		2018.8.27 10:35
→	(Head-1) X Offset Direction	Positive
	(Head-1) X Offset (mm)	000.0
	(Head-1) Y Offset Direction	Positive
	(Head-1) Y Offset (mm)	000.0
	(Head-2) X Offset Direction	Positive
	(Head-2) X Offset (mm)	000.0
	(Head-2) Y Offset Direction	Positive
	(Head-2) Y Offset (mm)	000.0

## 7.8 Function Config

On the **Manufacture Params Settings** page, move cursor to **Function Config** and press **Enter** . Press **←** **→** to modify options and press **Enter** to save settings.

**Figure7-8-1 Function Config Interface**

Function Config		2018.8.27 10:35
➡	Two Table Direction	X
	Two Table Home-Direction	Negative
	X1,X2 Head Space(mm)	0030.0
	Y1,Y2 Head Space(mm)	0000.0
	Y&U Axis For Feeding	Disable
	Y&U Axis Feeding Direction	Negative
	Pen-Function	Disable

**Table7-7-1 Function Config Instruction**

Name	Instruction
Two Tabel Direction	The direction of two rails, X or Y.
Two Tabel Home-Direction	If the distance between laser heads in X or Y direction is "0", but the cut graphics is still not aligned, then change the home-direction of two tables.
X1, X2 Head Space (mm)	The distance of laser heads in X direction.
Y1, Y2 Head Space (mm)	The distance of laser heads in Y direction.
Y&U Axis For Feeding	Enable or disable the function.

Y&U Axis Feeding Direction	Set the direction of Y&U axis feeding.
Pen-Function	Open or close this function.

In order to avoid deformation or position change of cutting material caused by u-axis feeding, the material can be fixed by blowing and pressure through Y-axis, and the 【Y&U Axis For Feeding】 function needs to be enabled. Other usage scenarios can be adjusted by users as required.

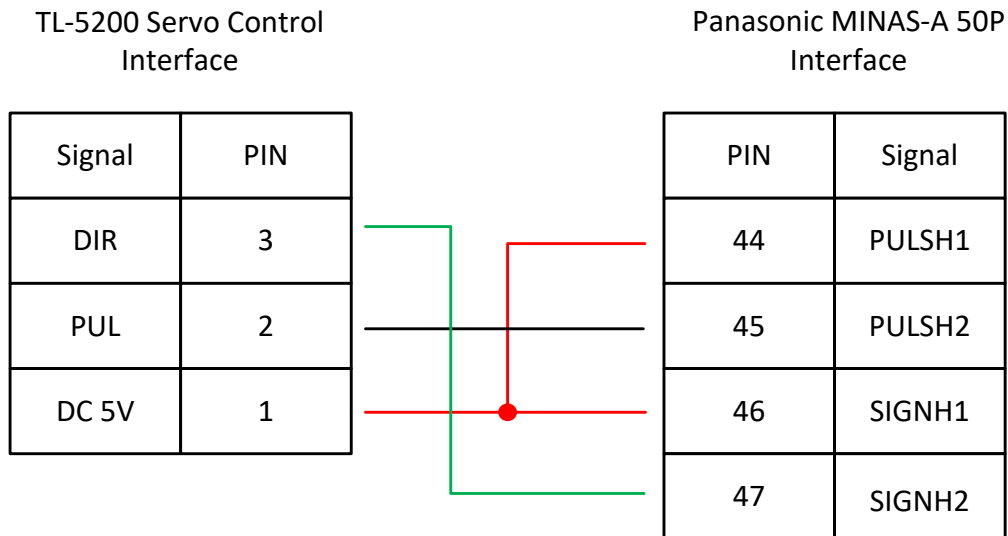
## 8. FAQ

1. The top bar displays local date and time. The date and time can be modified, which requires the cooperation of encryption software. If the time changes to 0.0.0, it means the battery in the panel has run out of power and can't set password for control card. The clock doesn't support power off relay function.
2. When the file name is in Chinese, it can only show 4 Chinese characters at most, and they are in common Chinese character library. A file name can display up to 8 characters when it uses number or English characters.

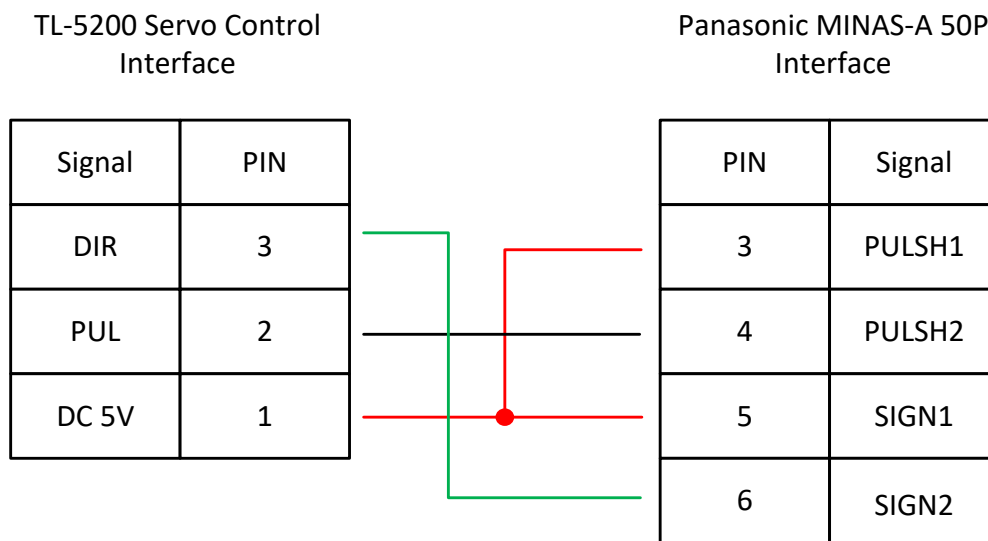
# Appendix 1: Wiring Diagram of Servo Driver

## 1. Panasonic A5 High Speed Pulse Wiring Diagram

**Figure 1-1 Panasonic A5 High Speed Pulse Wiring Diagram**



**Figure 1-2 Panasonic A5 Low Speed Pulse Wiring Diagram**



**Table1-1 Panasonic A5 Series Basic Setting Parameters**

Mode	Value	Instruction
Pr001	0	Control mode, must be set to position mode.
Pr007	3	Must be "Pulse + Direction" mode.
Pr005	1	<p>High-speed pulse connection mode, the parameter is set to "1", and the maximum pulse frequency is 3Mpps.</p> <p>Low speed pulse connection mode, the parameter is set to "0", and the maximum pulse frequency is 500Kpps.</p>

## 2. Yaskawa Wiring Diagram

Figure 2-1 Yaskawa Wiring Diagram

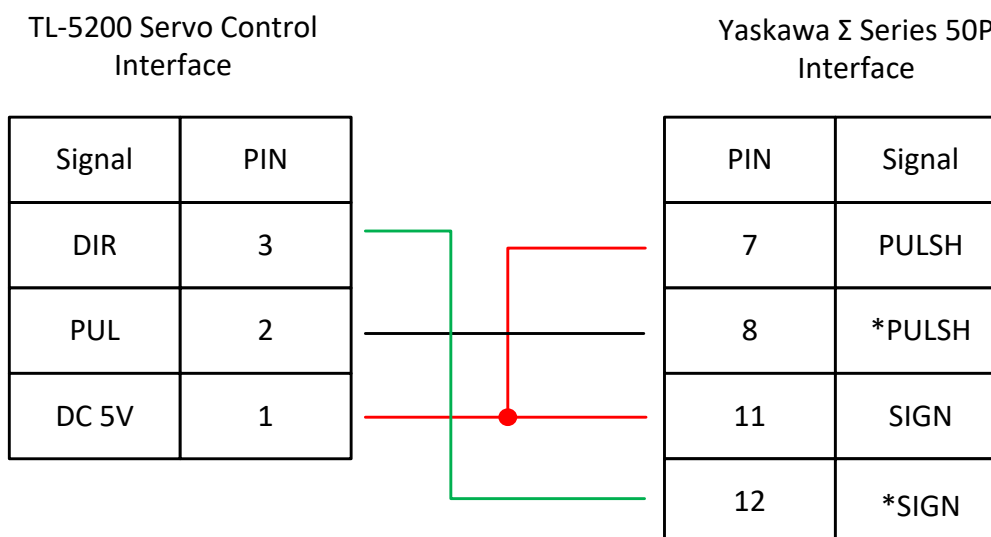


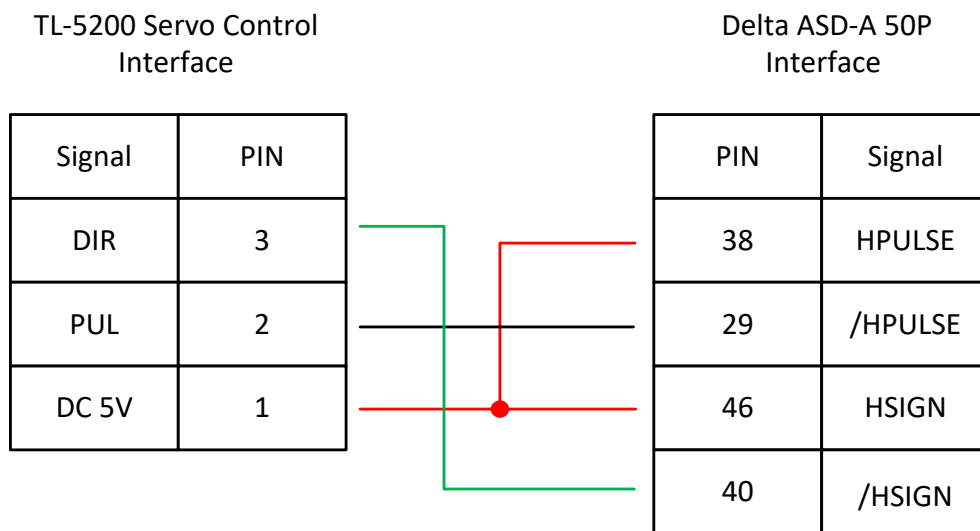
Table2-1 Yaskawa Σ Series Basic Setting Parameters

Mode	Value	Instruction
Pn000	001X	Position mode.
Pn00B	None	When single-phase power input, the parameter is set to "0100".
Pn200	2000H	<p>Positive logic: Pulse + Direction;</p> <p>0005H negative logic: Pulse + Direction;</p> <p>When the pulse frequency is less than 1Mpps, please select "0000H".</p> <p>When the pulse frequency reaches 1Mpps~4Mpps, please select "2000H".</p>

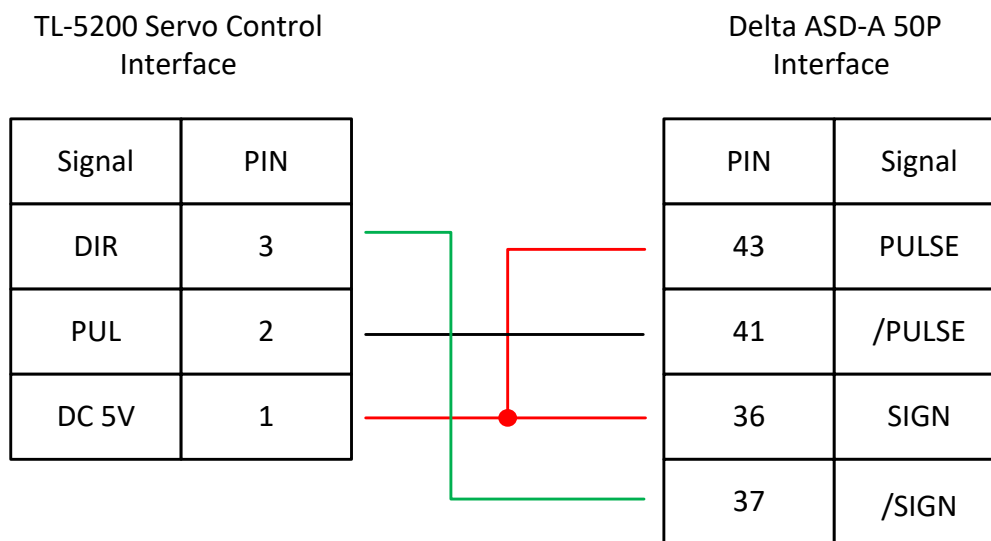
Pn50A	8100	Positive rolling side can be driven.
Pn50B	6548	Negative rolling side can be driven.

### 3. Delta A Series High Speed Pulse Wiring Diagram

**Figure 3-1 Delta A Series High Speed Pulse Wiring Diagram**



**Figure 3-2 Delta A Series Low Speed Pulse Wiring Diagram**



**Table3-1 Delta ASD-A Series Basic Setting Parameters**

Mode	Value	Instruction
P1-00	1102H	<p>Position control mode, negative logic: "Pulse + Direction".</p> <p>Set the parameter to "1102H" to open the high-speed differential signal, and the maximum pulse frequency is 4Mpps;</p> <p>Set the parameter to "0102H" low-speed pulse signal, and the maximum pulse frequency is 500K.</p>
P1-01	00	Select the location mode controlled by the external instruction.
P2-10	101	DI1 is set to SON servo enablement, and the logic is

		normally open.
P2-14	102	DI5 is set as ARST clear alarm function, the logic is normally open.
P2-12	007	DO5 is set as ALRM servo alarm function, the logic is normally closed.

#### 4. Sanyo R Series Wiring Diagram

Figure 4-1 Sanyo R Series Wiring Diagram

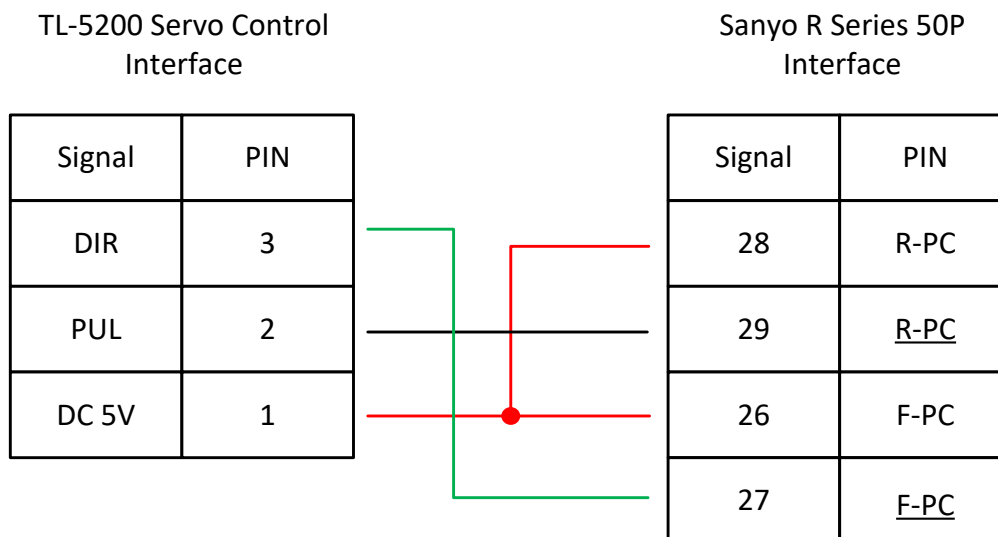


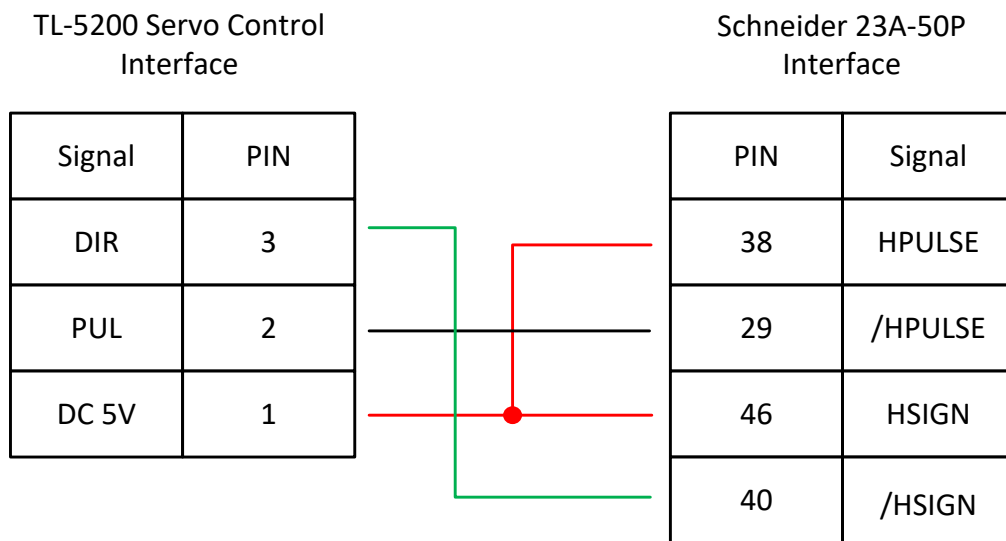
Table4-1 Sanyo R Series Basic Settings Parameters

Mode	Value	Instruction
SY08	00	Position mode.
Gr8.11	02	Pulse signal mode: Pulse + Direction.

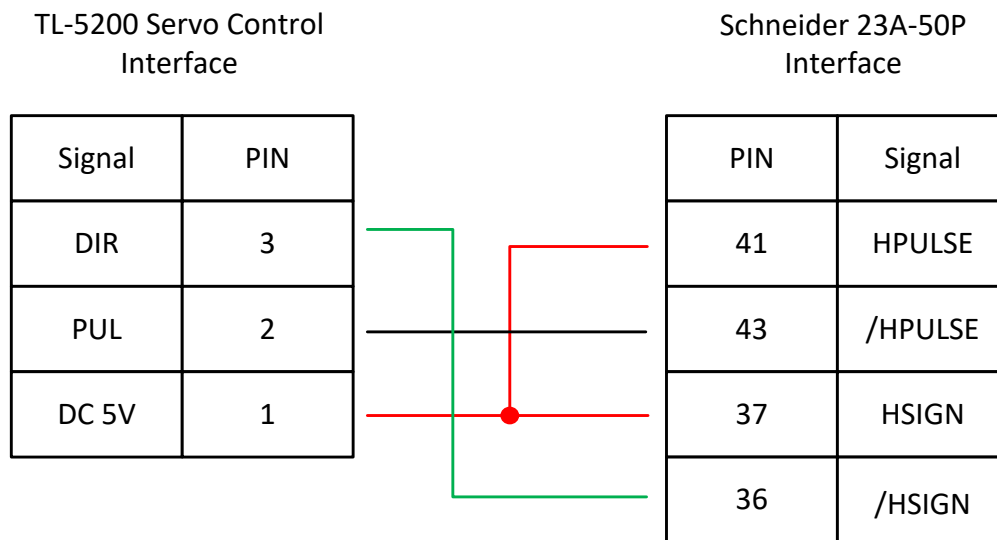
Gr9.00	00	Positive rolling side can be driven.
Gr9.01	00	Negative rolling side can be driven.

## 5. Schneider 23A High Speed Pulse Wiring Diagram

**Figure 5-1 Schneider 23A High Speed Pulse Wiring Diagram**



**Figure 5-2 Schneider 23A Low Speed Pulse Wiring Diagram**



**Table5-1 Schneider Lexium 23D Series Basic Settings Parameters**

Mode	Value	Instruction
P1-00	1102H	<p>Position control mode, negative logic: "Pulse + Direction".</p> <p>Set the parameter to "1102H" to open the high-speed differential signal, and the maximum pulse frequency is 4Mpps;</p> <p>Set the parameter to "0102H" low-speed pulse signal, and the maximum pulse frequency is 500K.</p>
P1-01	X00	Select the location mode controlled by the external instruction.
P2-10	101	Change the servo IN1 to SON function.

P2-11	0	We do not use IN2。
P2-13~P2-17	0	We do not use IN4~IN8。

## 6. Fuji A5 Series Wiring Diagram

Figure 6-1 Fuji A5 Series Wiring Diagram

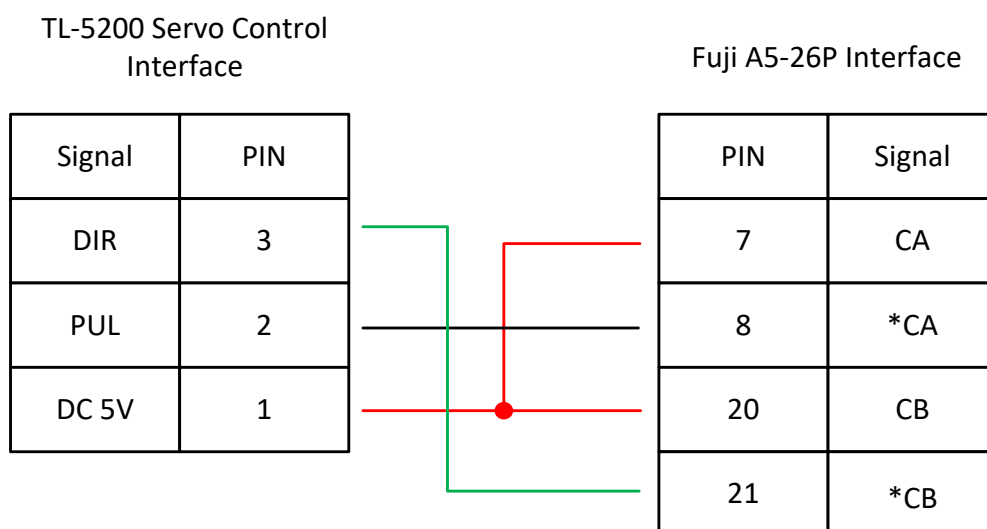
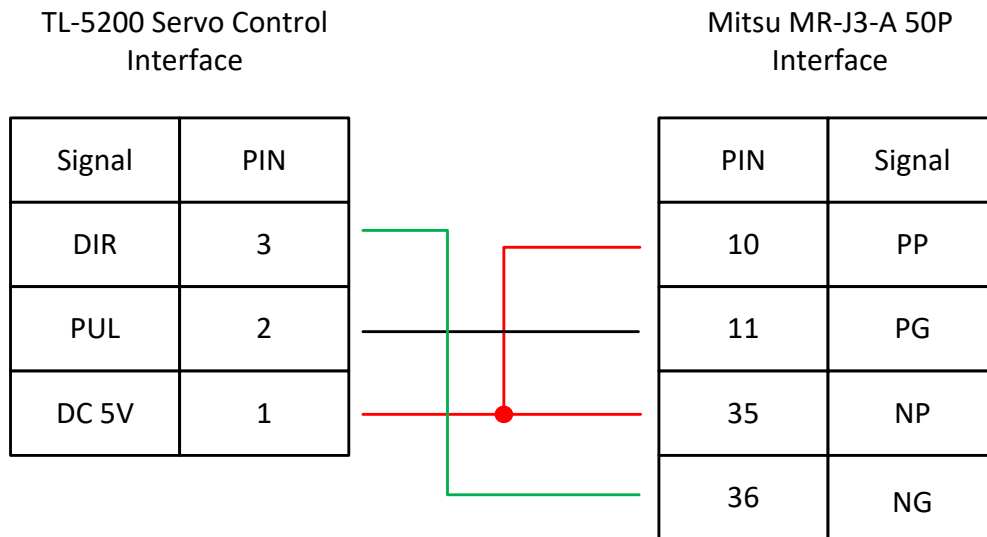


Table6-1 Fuji ALPHA 5 Series Basic Setting Parameters

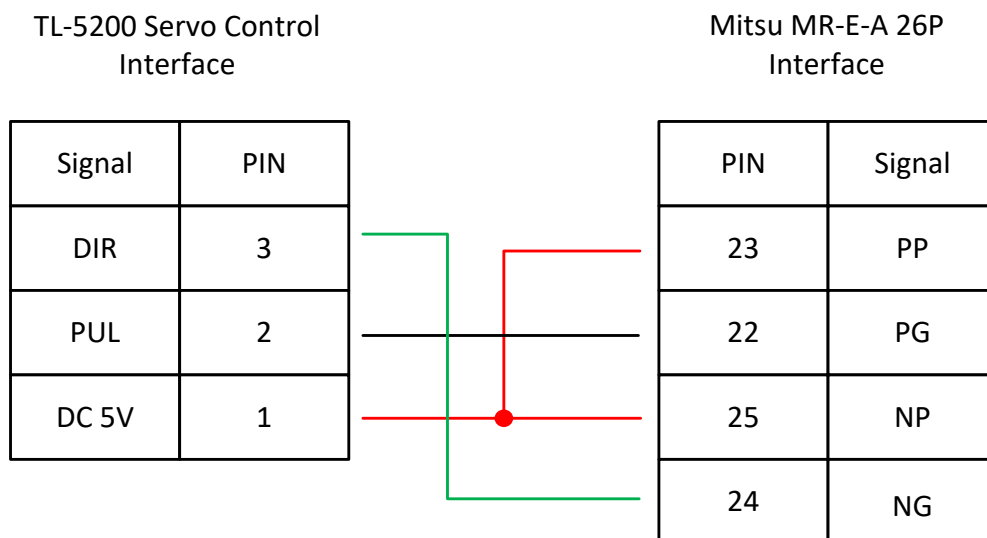
Mode	Value	Instruction
PA-101	0	Position control mode.
PA-103	0	Pulse + Direction, the maximum pulse frequency is 1Mpps.

## 7. Mitsu Series Wiring Diagram

**Figure 7-1 Mitsu J3 Series Wiring Diagram**



**Figure 7-2 Mitsu E Series Wiring Diagram**



**Table7-1 Mitsu MR-J3—A Series Basic Setting Parameters**

<b>Mode</b>	<b>Value</b>	<b>Instruction</b>
PA01	0	Control mode: Position mode.
PA13	0011	Negative logic: Pulse + Direction.

Notice: The maximum pulse frequency of Mitsu J3 Series is 1Mpps.